

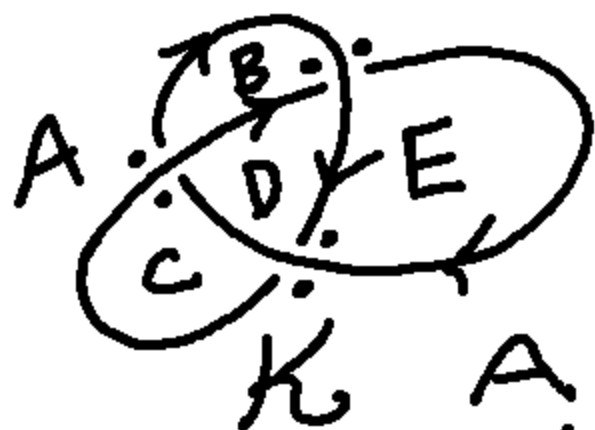
# A State Summation Invariant For Knotoids

L Kauffman, UIC  
joint work with  
N Dügüncü

1. Recall state sum for Conway-Alexander Polynomial  
(LHK, Formal Knot Theory, PUP 1981)

J.W. Alexander  $\frac{A \uparrow D}{B \downarrow C} \rightsquigarrow Ax + Bx + C + D$   
TAMS (1928) module relation

(Alex used  $Ax - Bx + C - D$ .  
Signs can be eliminated.)



$$\left. \begin{array}{l} Ax + Cy + D + B \\ Ax + Bx + D + E \\ Ax + Ex + D + C \end{array} \right\}$$

$$\left( \begin{array}{l} R \doteq S \\ \text{means} \\ R = \pm \lambda^N S \end{array} \right)$$

	A	B	C	D	E
A	$\lambda$	1	$\lambda$	1	0
B	$\lambda$	$\lambda$	0	1	1
C	$\lambda$	0	1	1	$\lambda$

$M(K)$

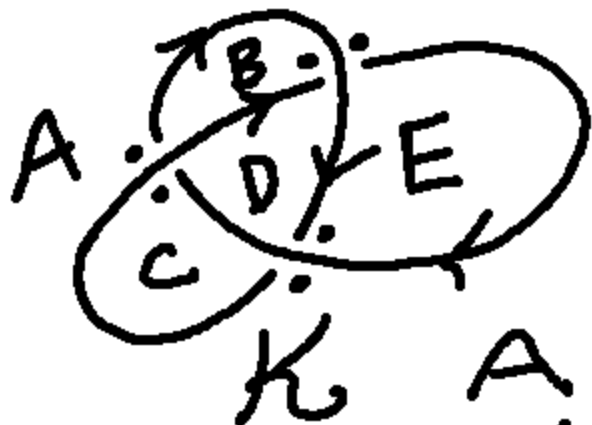
(remove two adjacent region columns)

$$\Delta_K(\lambda) \doteq \text{Det}(M(K))$$

$$= \lambda \begin{vmatrix} 1 & 1 \\ 1 & \lambda \end{vmatrix} - \begin{vmatrix} 0 & 1 \\ 1 & \lambda \end{vmatrix}$$

$$= \lambda(\lambda - 1) + 1 = \lambda^2 - \lambda + 1$$

$$\Delta_K(\lambda) \doteq \lambda^2 - \lambda + 1$$



$$\left. \begin{aligned} Ax + Cx + D + B \\ Ax + Bx + D + E \\ Ax + Ex + D + C \end{aligned} \right\}$$

$$\left( \begin{aligned} R &\doteq S \\ \text{means} \\ R &= \pm X^N S \end{aligned} \right)$$

$K$

	A	B	C	D	E
1.	$X$	1	$X$	1	0
2.	$X$	$X$	0	1	$X$
3.	$X$	0	1	$X$	$X$

$M(K)$

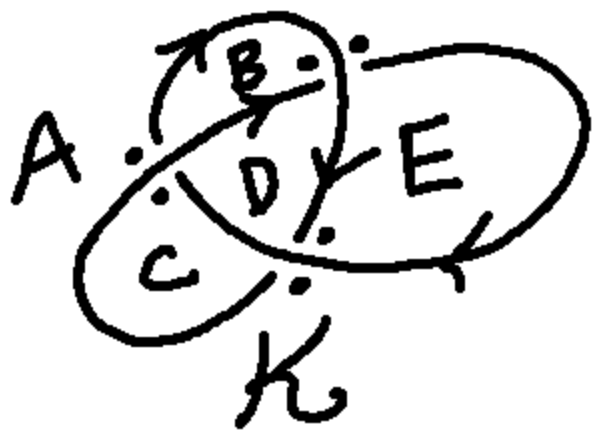
(remove two adjacent region columns)

$\neq 0$   
 $\left\{ \begin{aligned} \text{Terms in} \\ \text{Det}(M) \end{aligned} \right\}$



$\leftrightarrow$   $\left\{ \begin{aligned} \text{Regions Chosen} \\ \text{Crossings.} \\ \text{Each crossing} \\ \text{chosen once.} \end{aligned} \right\}$

Marker States  $\mathcal{L}(K)$



$\text{sgn}(S)$   
 $\parallel \text{def}$   
 $(-1)^{b(S)}$   
 $b(S) =$

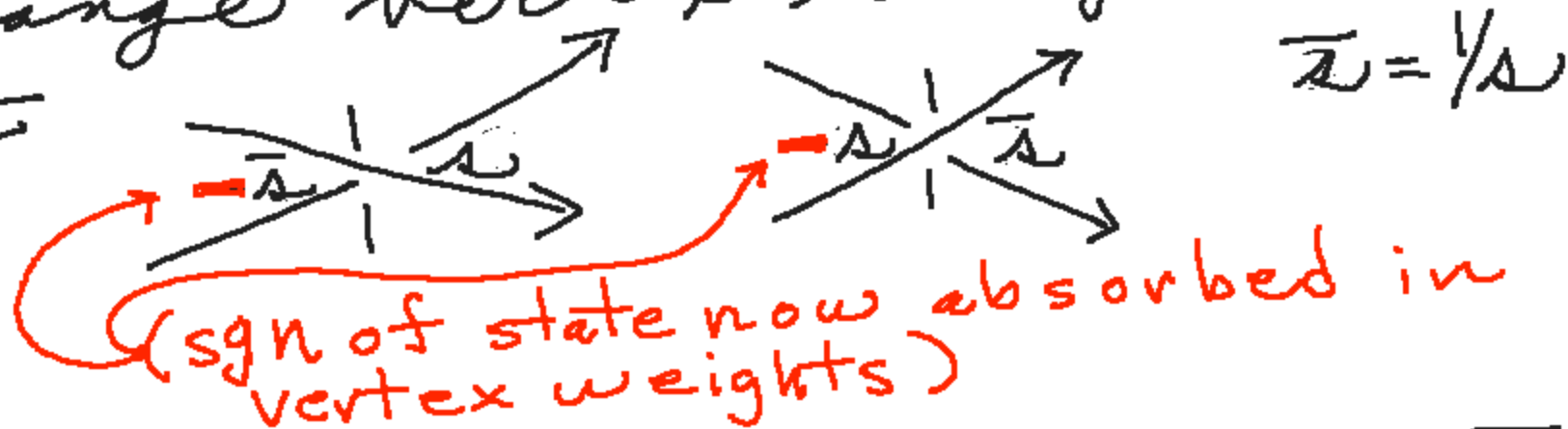


Permutation  
 Sign is  
 Replaced  
 by the  
 "black hole  
 count"

$$\Delta_K(\pi) = \sum_{S \in \mathcal{S}} \text{sgn}(S) \langle K|S \rangle$$

$\underbrace{\qquad\qquad\qquad}_{\pi \text{ or } \pi^2 \text{ or } \pi^4 \text{ or } \dots}$

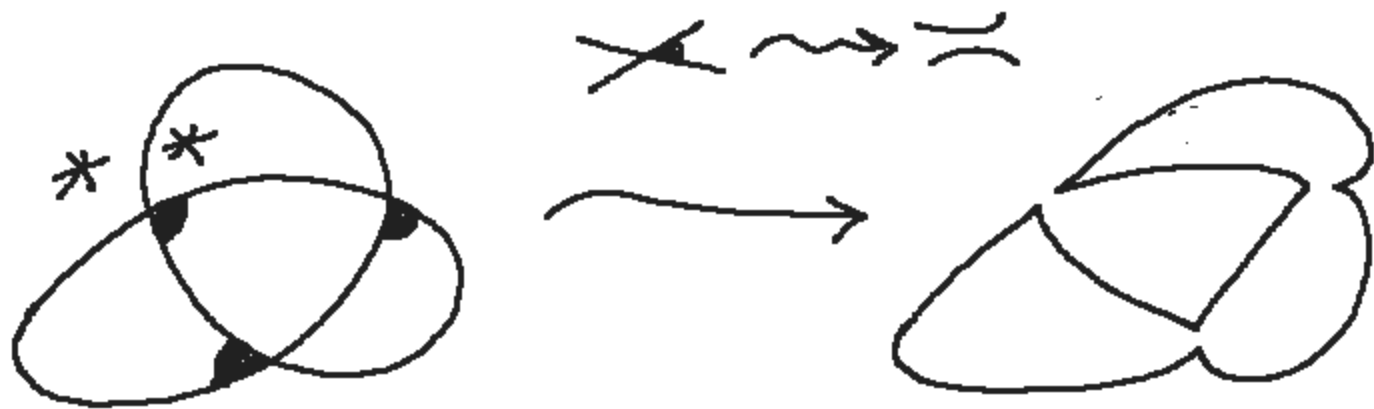
For Conway, Alexander  
change vertex weights  
to



$$z = a - \bar{a}$$

$$\nabla_K = \sum_{S \in \Delta} \langle K | S \rangle$$

$$\left. \begin{array}{l} \nabla_{\vec{s}}^{\uparrow} - \nabla_{\vec{s}}^{\downarrow} = z \nabla_{\vec{s}}^{\rightarrow} \\ K \sim K' \\ \implies \nabla_K = \nabla_{K'} \end{array} \right\}$$



States are in 1-1 correspondence  
with single cycle  
smoothings of the diagram.

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States are in  
1-1 correspondence  
with maximal  
trees in the  
checkerboard  
graph.

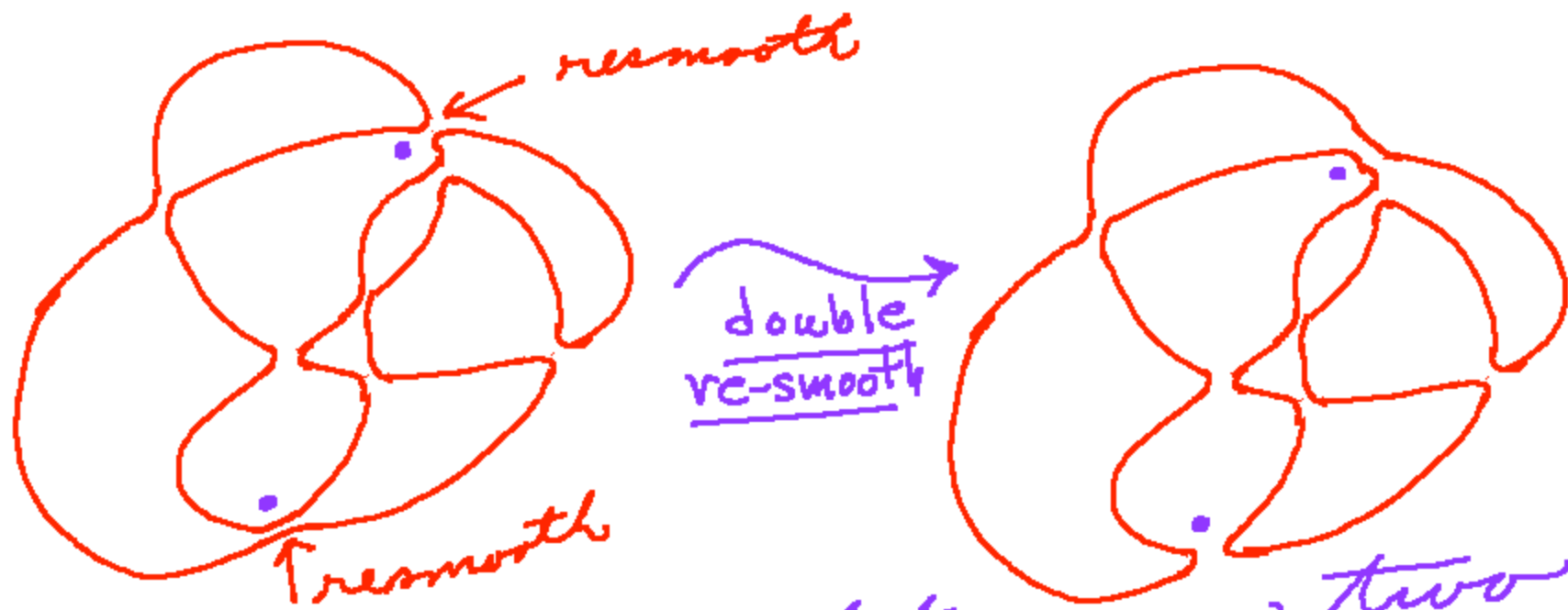


COT

Clack Theorem. The states of a diagram form a lattice with a unique locked state and a unique counter-locked state. Clocking moves connect any two states.

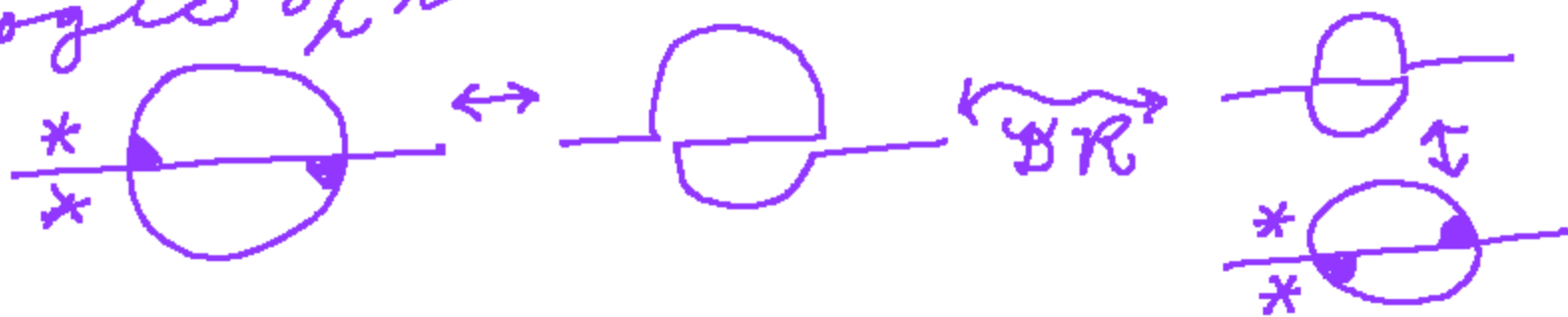
Individual clocking moves change the sign of the state.

(It is a consequence of the COT that the state sum computes the Det(M).)

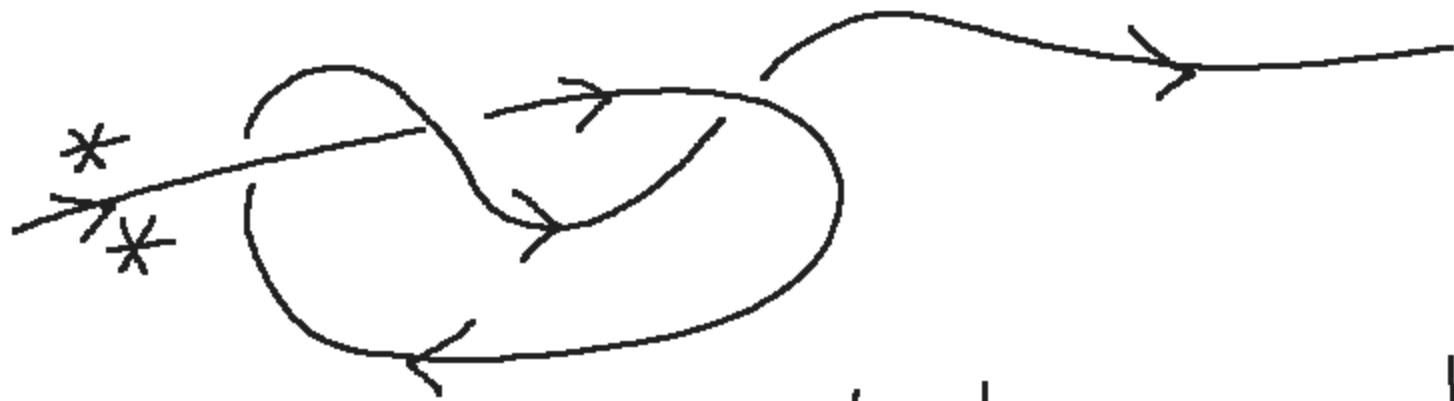


It is the case that any two states can be connected by sequences of double-re-smoothings.

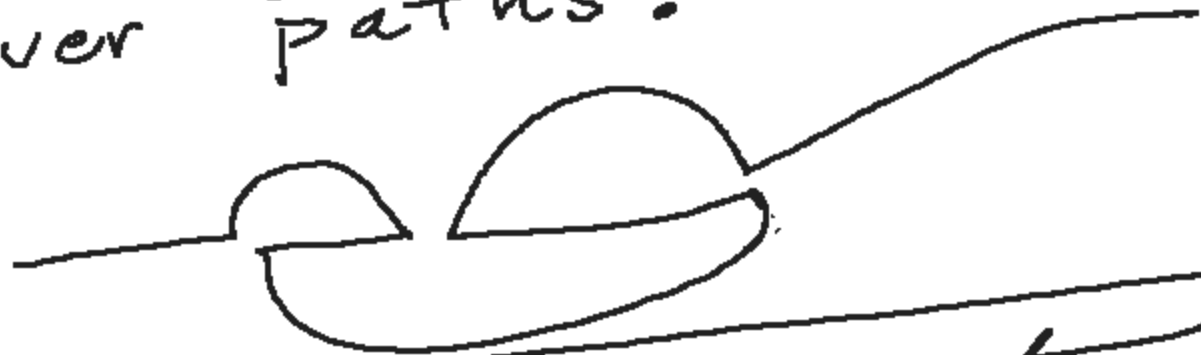
This is the underlying logic of the Clock of Heaven.







For long knots & links, we have a standard choice of deleted regions. The sum is over paths.



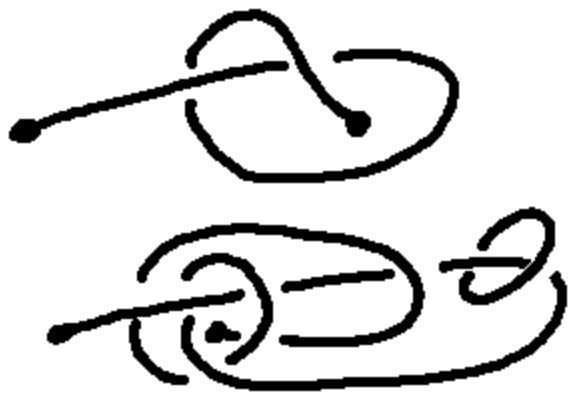
All of this applies to the bracket poly/foam poly with different vertex weights.

# A State Sum Invariant for Knotoids

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Joint work with Neslihan Gügümcü.

2. A knotoid is a diagram with endpoints in possibly different regions, taken up to Reidemeister moves that avoid endpoints.



These knotoids generalize  $(1-1)$  tangles.  
Term due to Turaev?

A knotoid (V. Turaev) is a knot diagram with two ends.  
The ends can be in different regions of the diagram.  
We study knotoids up to Reidemeister moves.  
The moves do not move arcs across the ends of  
the diagrams.



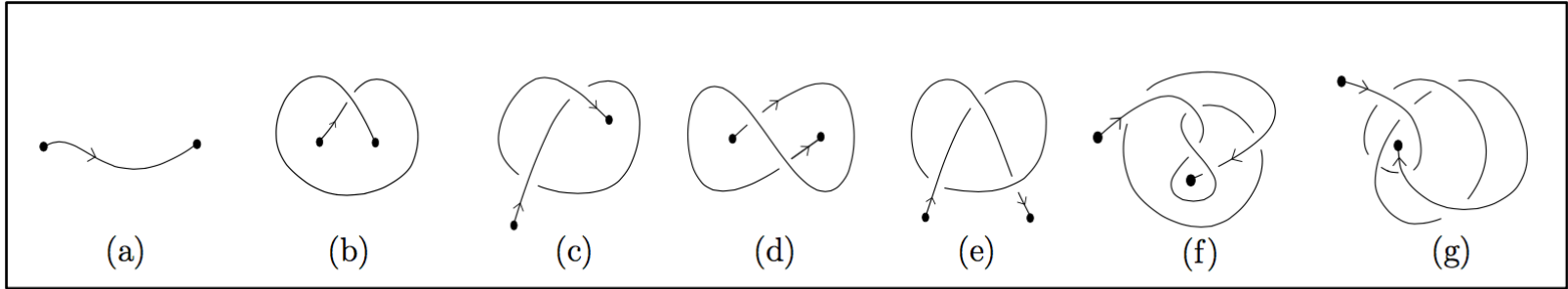
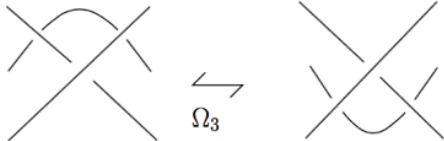
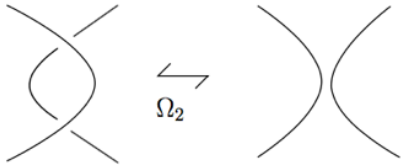
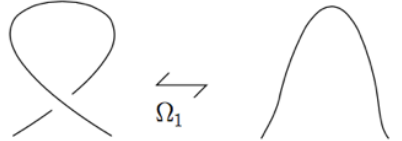
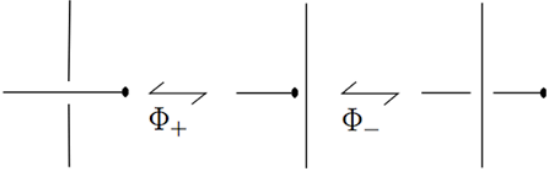


FIGURE 1. **Knotoid diagrams**



(a)  $\Omega_{i=1,2,3}$ - moves



(b) **Forbidden knotoid moves**

**2.1. An Interpretation of Classical Knotoids in 3-Dimensional Space.** Let  $K$  be a knotoid diagram in  $\mathbb{R}^2$ . The plane of the diagram is identified with  $\mathbb{R}^2 \times \{0\} \subset \mathbb{R}^3$ .  $K$  can be embedded into  $\mathbb{R}^3$  by pushing the overpasses of the diagram into the upper half-space and the underpasses into the lower half-space in the vertical direction. The tail and the head of the diagram are attached to the two lines,  $t \times \mathbb{R}$  and  $h \times \mathbb{R}$  that pass through the tail and the head, respectively and is perpendicular to the plane of the diagram. Moving the endpoints of  $K$  along these special lines gives rise to embedded open oriented curves in  $\mathbb{R}^3$  with two endpoints of each on these lines.

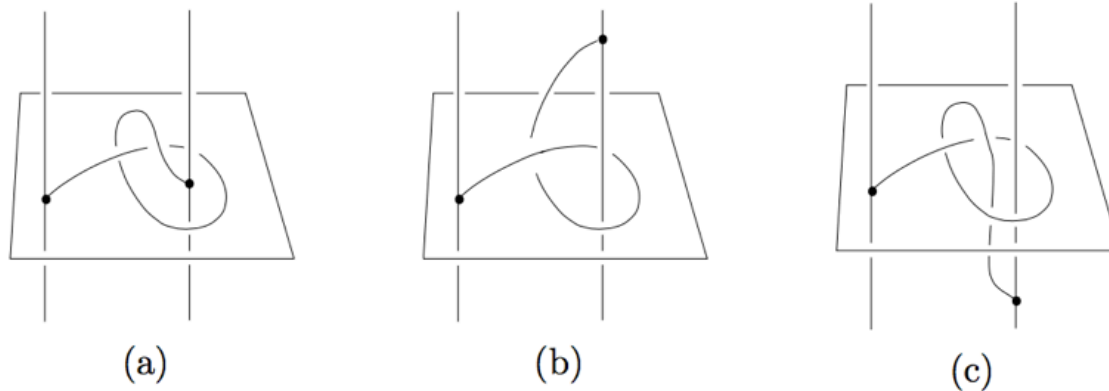
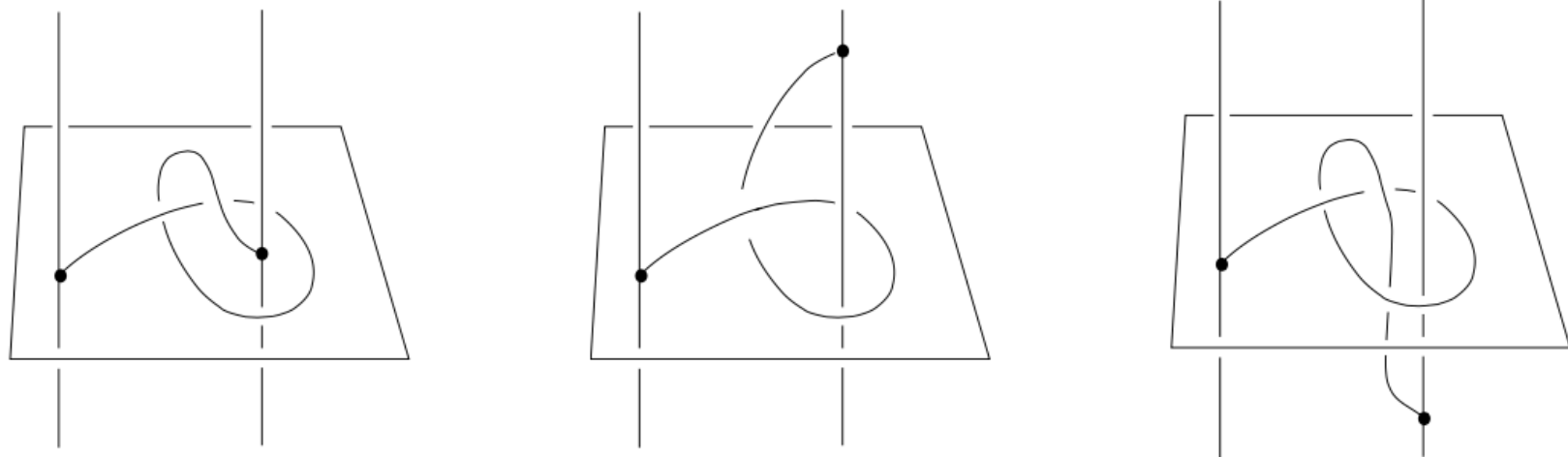
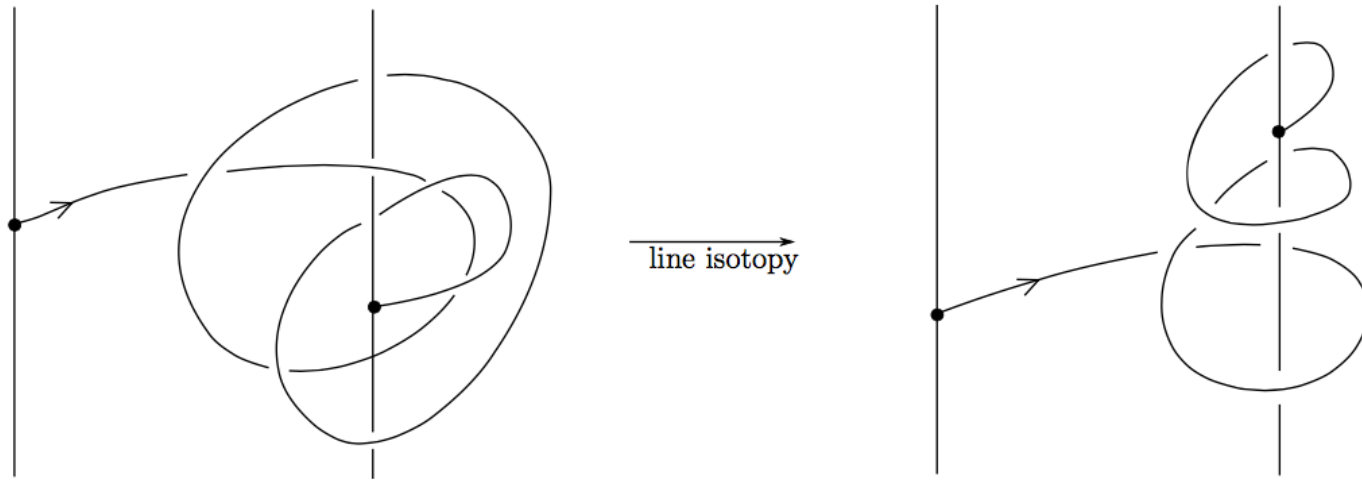


FIGURE 3. Curves in  $\mathbb{R}^3$  obtained by the knotoid diagram in Figure 1(c)



An embeded arc in  $R^3$  becomes a knotoid on taking a generic projection to a plane.

Restricting isotopies of the arc to endpoint motions on the parallel lines (perpendicular to the plane) and otheswise in the complement of the two lines, preserves the knotoid type of the projection.



**Descending Knotoid  
diagrams are unknotted.**

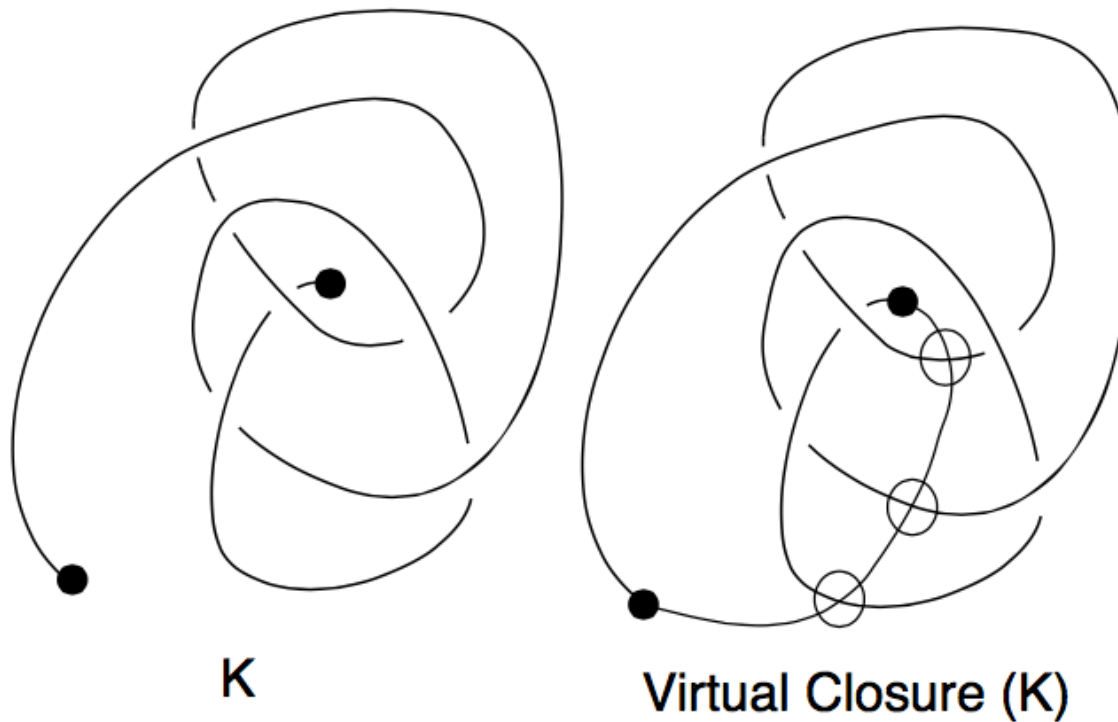
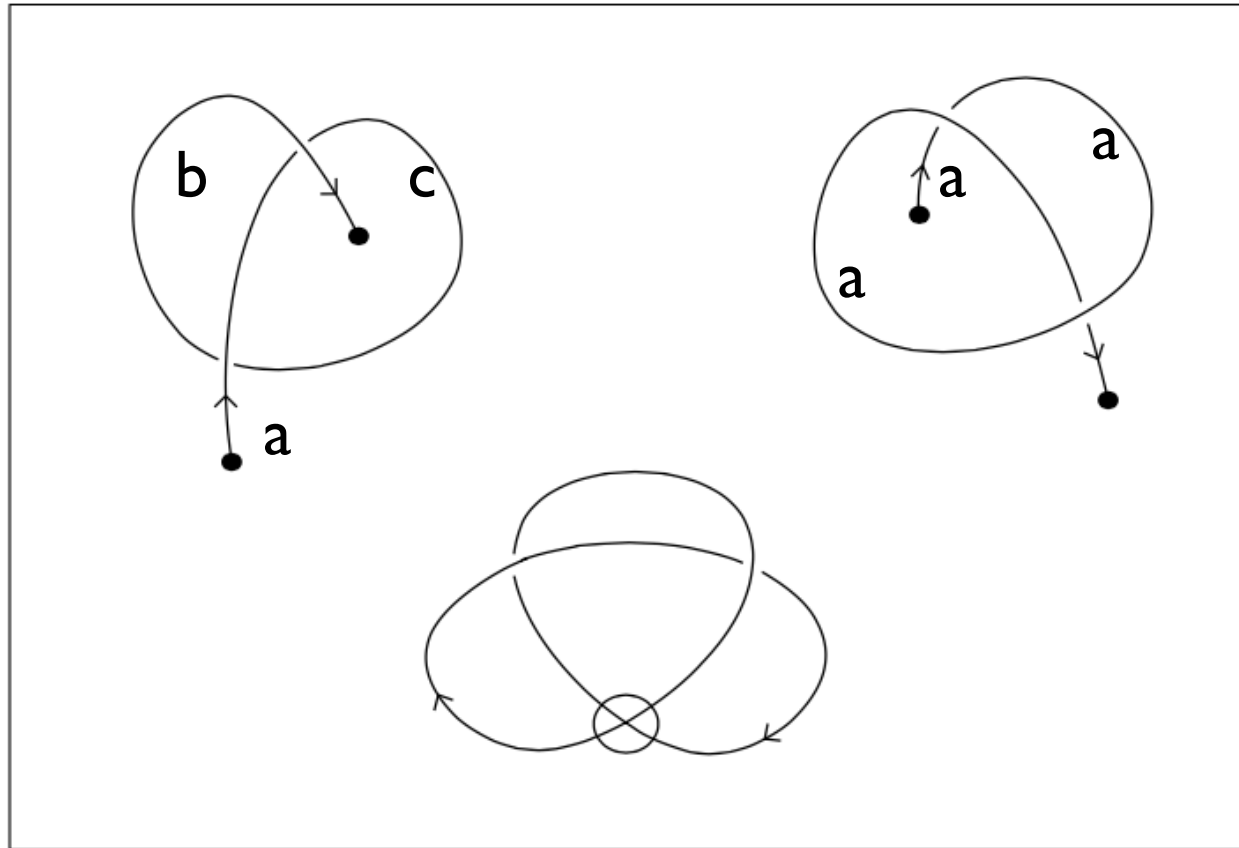


Figure 14: **Knotoid and Its Virtual Closure**

The virtual closure of a knotoid is supported in genus one (add a handle to the 2-sphere).



## Two Distinct Knotoids with the same Virtual Closure



# Bracket Polynomial for Knotoids



A-smoothing B-smoothing

$$\langle \text{A-crossing} \rangle = A \langle \text{A-smoothing} \rangle + A^{-1} \langle \text{B-smoothing} \rangle$$

$$\langle \text{B-crossing} \rangle = A^{-1} \langle \text{A-smoothing} \rangle + A \langle \text{B-smoothing} \rangle$$

$$\langle \text{arc} \rangle = 1$$

$$\langle K \circ \bigcirc \rangle = d \langle K \rangle$$

## Bracket Calculation

$$\langle \text{Diagram 1} \rangle = A \langle \text{Diagram 2} \rangle + A^{-1} \langle \text{Diagram 3} \rangle$$

Diagram 1: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right.

Diagram 2: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right. The crossings are in the opposite order to Diagram 1.

Diagram 3: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right. The crossings are in the opposite order to Diagram 1.

$$= A( A \langle \text{Diagram 4} \rangle + A^{-1} \langle \text{Diagram 5} \rangle ) + A^{-4} \langle \text{Diagram 6} \rangle$$

Diagram 4: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right.

Diagram 5: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right.

Diagram 6: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right.

$$= (A^2 + 1 - A^{-4}) \langle \text{Diagram 7} \rangle$$

Diagram 7: A strand with two crossings, one above the other, forming a loop. The strand starts from the bottom left and ends at the top right.

Conjecture: The bracket polynomial detects the unknotted knotoid.

Discussion: This conjecture includes the well-known conjecture that the Jones polynomial detects the unknot.

Note that the corresponding conjecture for virtual knots is false. There are non-trivial non-classical virtual knots with unit Jones polynomial. And there are examples of such virtual knots of genus one. This means that we conjecture that such virtual knots are not in the image of the closure map from knotoids.

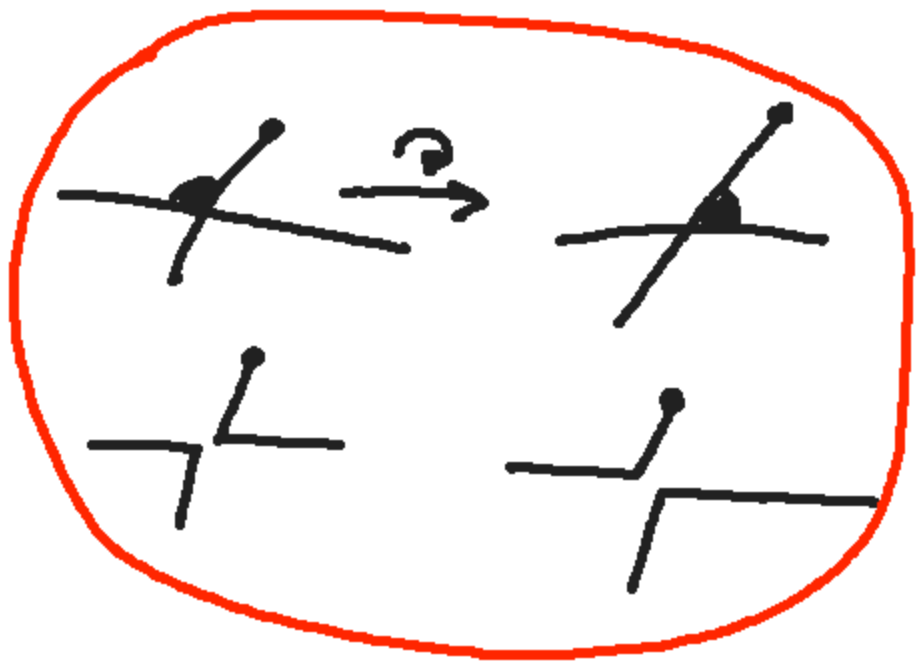
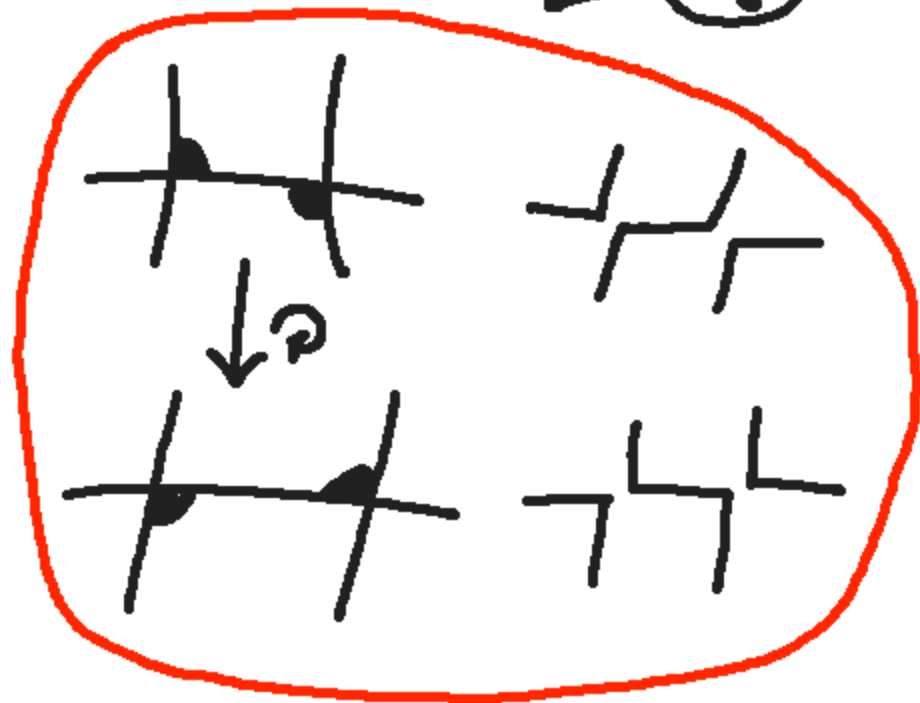
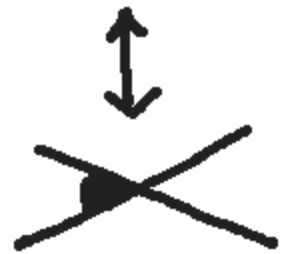
In this talk we show how the FKT (Formal Knot Theory) state summation for Alexander-Conway polynomial generalizes to a potential function  $\nabla_K(s)$  for knotted.



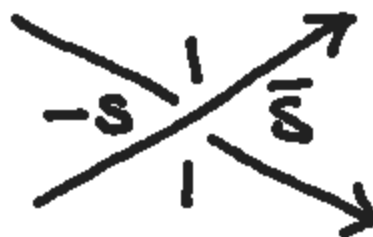
States <sup>non-crossing</sup>  
 $= \{ \text{paths from } i \rightarrow f \}$

Marker States

# Two Types of Clocking Move



Here we show how to use the path states to define a Conway potential function  $\nabla_K(s)$ .

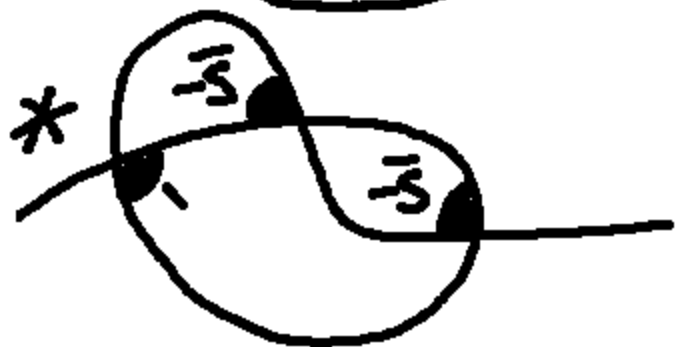
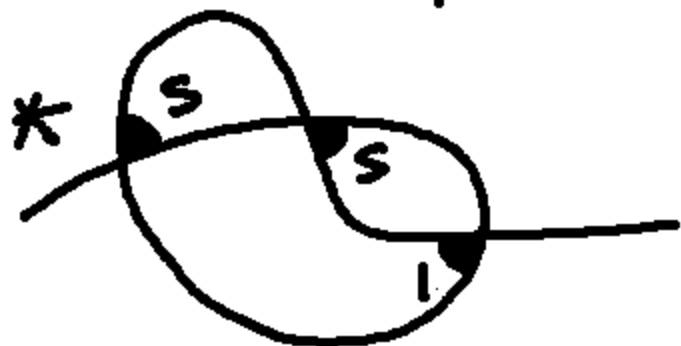


vertex weights.

$$\nabla_K(s) = \sum_{\alpha \in \text{Paths}(K)} \langle K | \alpha \rangle$$

$\langle K | \alpha \rangle =$  Product of the vertex weights touched by markers in  $\alpha$ .

# The Classical Case



$$\begin{aligned}\nabla_T &= s^2 - 1 + \bar{s}^2 \\ &= (s - \bar{s})^2 + 1\end{aligned}$$

$$\nabla_T = z^2 + 1, \quad z = s - \bar{s}$$

$$\begin{aligned}\Delta_K(t) &\doteq \nabla_K(s = \sqrt{t}) \\ &= t - 1 + t^{-1} \\ &\doteq t^2 - t + 1\end{aligned}$$

Alexander



In the classical case  
we have that for  $z = s - \frac{1}{2}$ ,

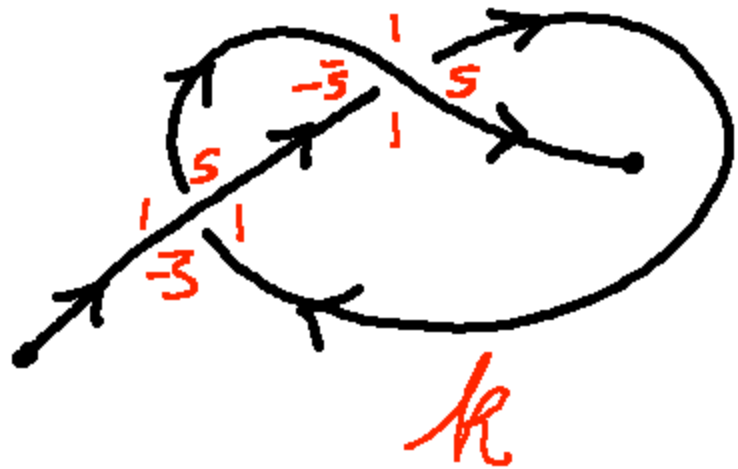
$$\nabla_{\rightarrow} - \nabla_{\leftarrow} = z \nabla_{\rightarrow}$$

if  $\Delta_K(t) = \text{alex poly}$

then  $\Delta_K(t) \doteq \nabla_K(s = \sqrt{t})$ .

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We take leave of these  
properties for the  
protoids.



$$\nabla_R = S^2 + S - \bar{S}$$

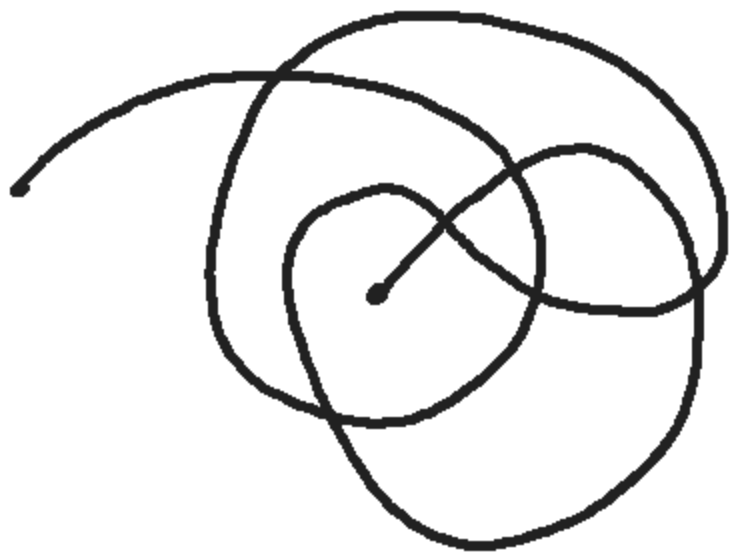

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The FKT Clock Theorem generalizes so that the states of a knotoid diagram form a lattice with unique clocked state (top) and counterclocked state (bottom).

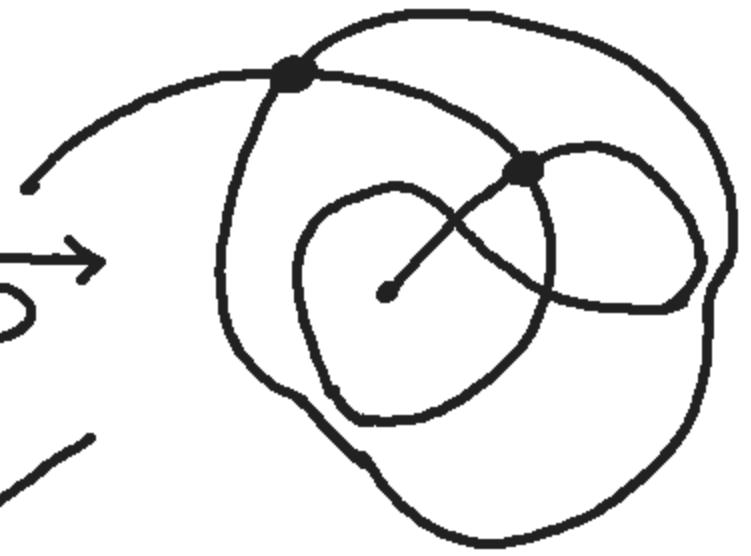


The clocked state generates all other states via the two types of clocking moves.

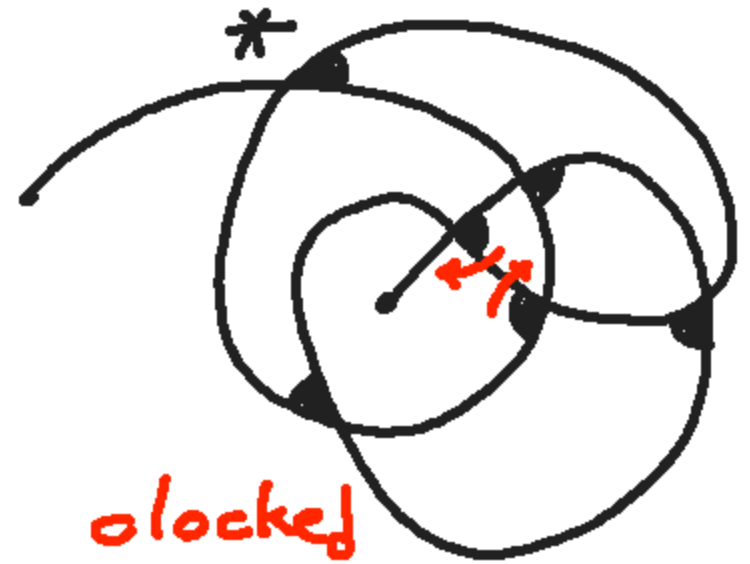
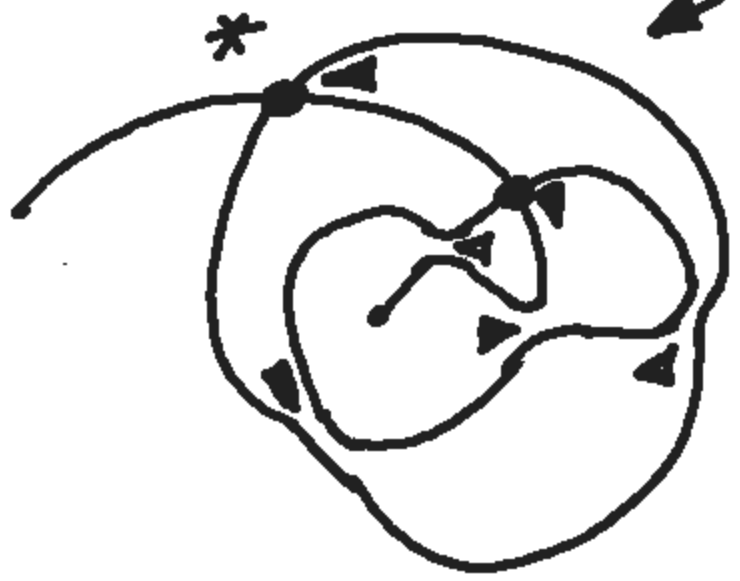
The clocked state can be constructed by a "shelling process".



A



A



olocked

As in the classical case,  
 these path-states for knotoids  
 can be applied to the bracket  
 expansion:



Analogy with trees  
 expansion for Tutte Poly.

so that with  
 appropriate  
 vertex sets  
 $\langle K \rangle = \sum \langle K | \alpha \rangle$   
 $\alpha \in \text{Paths}$   
 and this can  
 be examined  
 for Khovanov  
 Homology (Knotoids).

Main

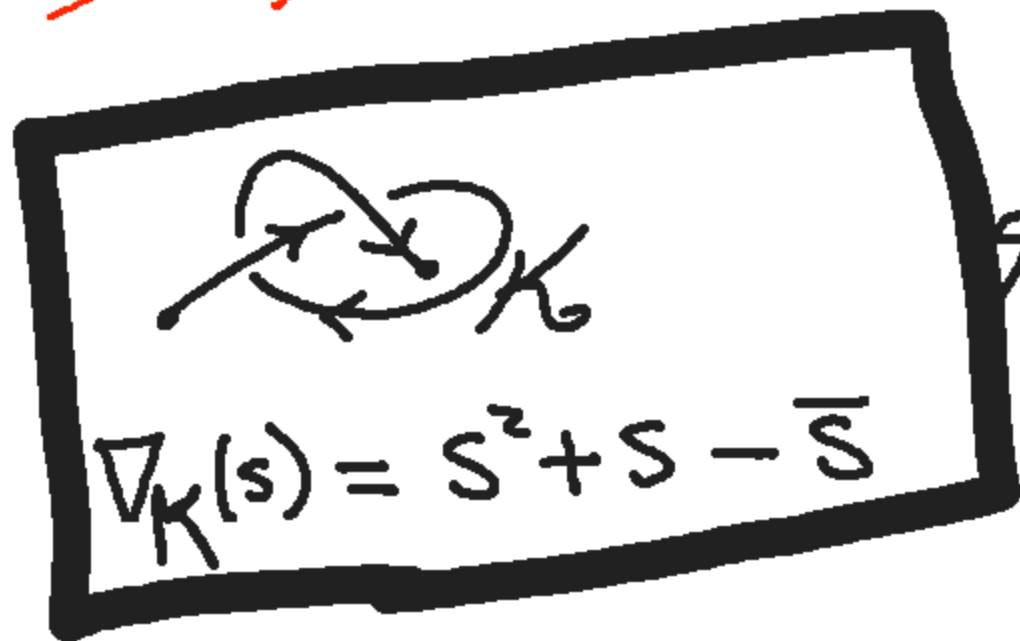
Theorem. a)  $\nabla_K(s)$  is a knotoid invariant.

b)  $\nabla_{K^*}(s) = \nabla_K(\bar{s})$

c)  $\nabla_{\vec{K}}(s) = \nabla_{\vec{R}}(-\bar{s})$

$K^*$  = Mirror image of  $K$

$\vec{K}, \vec{K}$  Two orientations of  $K$



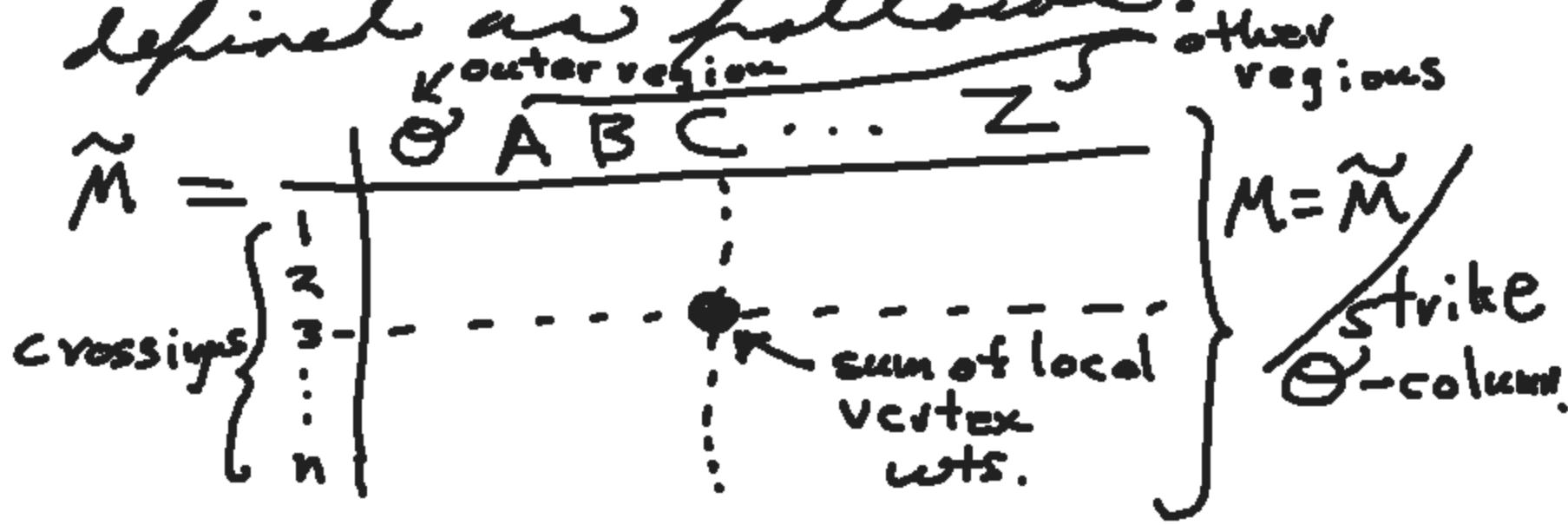
Here we have  $K \not\cong K^*$  and  $\vec{K} \not\cong \vec{K}$ .

In the classical case, the  
 Conway potential function  
 is equivalent to a determinant.

In the knotoid generalization

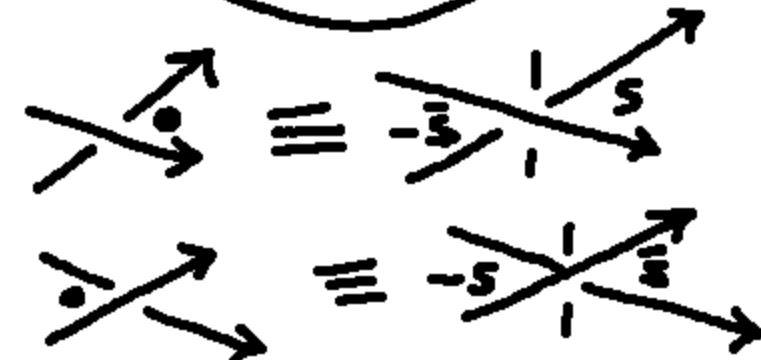
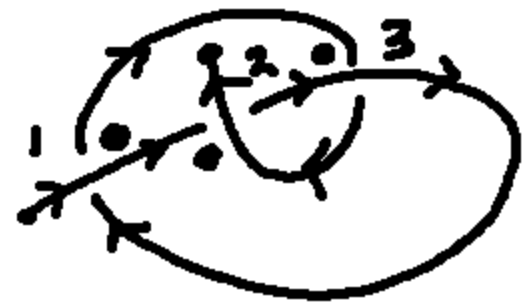
$$\nabla_K(s) = \text{Permanent}(M(K))$$

where the matrix  $M(K)$  is  
 defined as follows:









	0	A	B	C
1	$1-s$	$s$	$0$	$1$
2	$0$	$1+s$	$1$	$-s$
3	$1$	$-s$	$1$	$s$

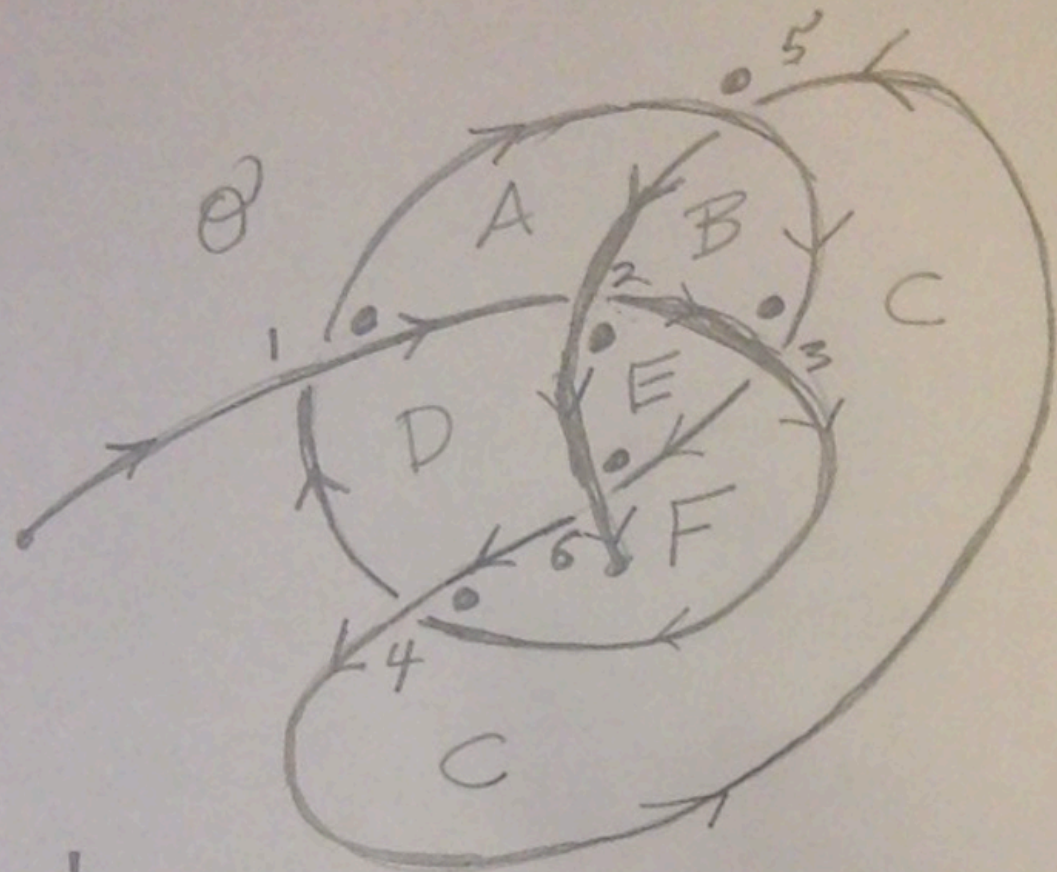
$= M$

$$\Delta_k(s) = \text{Perm}(M)$$

In[3]:=

```
MM = {{s, 0, 1}, {1 + 1/s, 1, -s}, {-s, 1, 1/s}};
Expand[Simplify[Expand[Permanent[MM]]]]
```

Out[4]=  $2 + \frac{1}{s} - s - s^2$



	$\theta$	A	B	C	D	E	F
1	$1-s$	$s$	0	0	1	0	0
2	0	$-s$	1	0	1	$s$	0
3	0	0	$-s$	1	0	1	$s$
4	$s$	0	0	1	1	0	$-s$
5	$-s$	1	$s$	1	0	0	0
6	0	0	0	0	1	$-s$	$s+1$

```

MMM = {{s, 0, 0, 1, 0, 0}, {-1/s, 1, 0, 1, s, 0},
        {0, -s, 1, 0, 1, 1/s}, {0, 0, 1, 1, 0, -s},
        {1, 1/s, 1, 0, 0, 0}, {0, 0, 0, 1, -s, +1/s}};

```

```

MatrixForm[MMM]

```

```

Expand[Simplify[Expand[Permanent[MMM]]]]

```

MatrixForm=

$$\begin{pmatrix} s & 0 & 0 & 1 & 0 & 0 \\ -\frac{1}{s} & 1 & 0 & 1 & s & 0 \\ 0 & -s & 1 & 0 & 1 & \frac{1}{s} \\ 0 & 0 & 1 & 1 & 0 & -s \\ 1 & \frac{1}{s} & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & -s & \frac{1}{s} \end{pmatrix}$$

$$= -\frac{1}{s^3} + \frac{1}{s^2} + \frac{2}{s} - 2s$$

This work is new and there are a number of questions. We expect

- a)  $\nabla_K$  is NP hard for knotted. The transition from det to perm is serious.
- b) The path state structure can be used to define a Knotoid Floer Homology with the states generating the chain complex.

Thank you for your  
attention!

