

# LECTURE 33 Mon 11/25

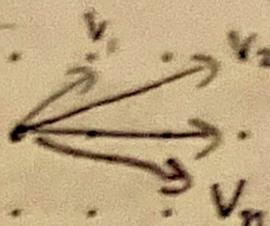
- Plan: Prof. Postnikov will go over stuff from his talk at the institute (what he was doing last week instead of being here)
- pset 2 will be posted today due Fri 12/6, presentations Mon 12/9

Matroids  $\supset$  Positroids

Polymatroids  $\supset$  polypositroids

Motivation for matroids

0. Configuration of vectors  $v_1, v_2, \dots, v_n \in \mathbb{F}^k$



Record the linear (in)dependence data between them

Now will give 3 kryptomorphic def of matroid:

1. Set of bases  $M \subseteq \binom{[n]}{k}$  satisfying (Strong) Exchange axiom

usual version

$$\forall I, J \in M, \forall i \in I$$

$$\exists j \in J \text{ s.t. } (I \setminus \{i\}) \cup \{j\} \in M$$

strong version

$$(J \setminus \{j\}) \cup \{i\} \in M \text{ to}$$

Exercise: Prove weak & strong versions equivalent

2. rank function  $\rho: 2^{[n]} \rightarrow \mathbb{Z}$

(think of it as counting # lin. ind. vectors in set)

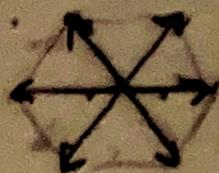
$$I \text{ basis iff } |I| = k = \text{rk } M \text{ and } \rho(I) = k$$

3. Matroid Polytope  $P = \text{conv}(\sum_{i \in I} e_i \mid I \in M)$

GGMS:  $P$  is a matroid polytope iff

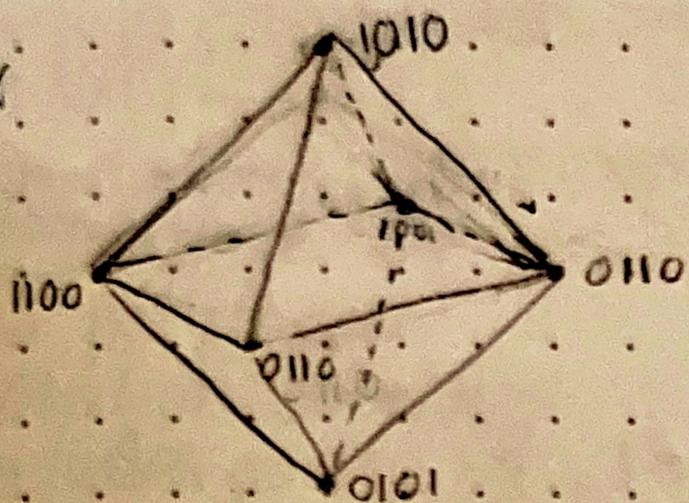
- all vectors are binary vectors.
- all edges parallel to  $e_i - e_j$  (roots) for some  $i, j$

e.g.  $n=3$



hypersimplex

$$\Delta_{24} =$$

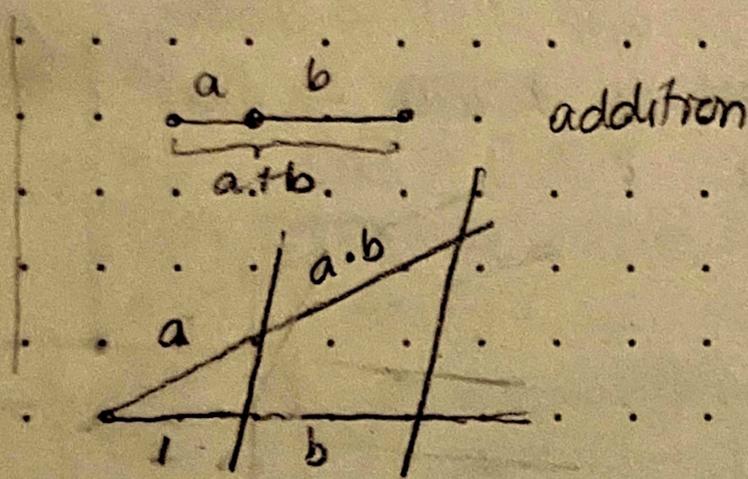
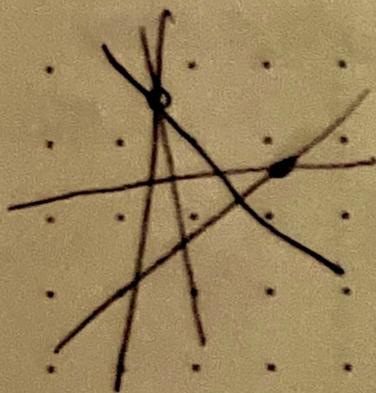


For matroids can take (connected?) parts of this  
 NOT, for example, the line  $1010 \rightarrow 0101$

Minor Universality:

Thm: Realization space of  $M$  can be arbitrarily complicated (as bad as anything can be in algebraic geometry)

Ex Can represent  $rk 3$  matroid as collection of lines on plane  
 Care if they pass through the same point



0. positroids  $\stackrel{\text{def}}{=} \equiv$  matroids realizable by a real matrix

$$A = \begin{bmatrix} | & & | \\ v_1 & \dots & v_n \\ | & & | \end{bmatrix} \text{ s.t. all maximal minors } \Delta_I(A) \geq 0$$

determinants of  $k \times k$  submatrices  $\rightarrow$

If  $\det > 0$  is basis, if  $\det = 0$  then not

- 1. Bases ✓
  - 2. Rank function ✓
  - 3. Matroid polytopes ✓
- (Just add some additional conditions from before)

Polymatroids

0. Motivation: Configuration of linear subspaces (no longer just lines)

