

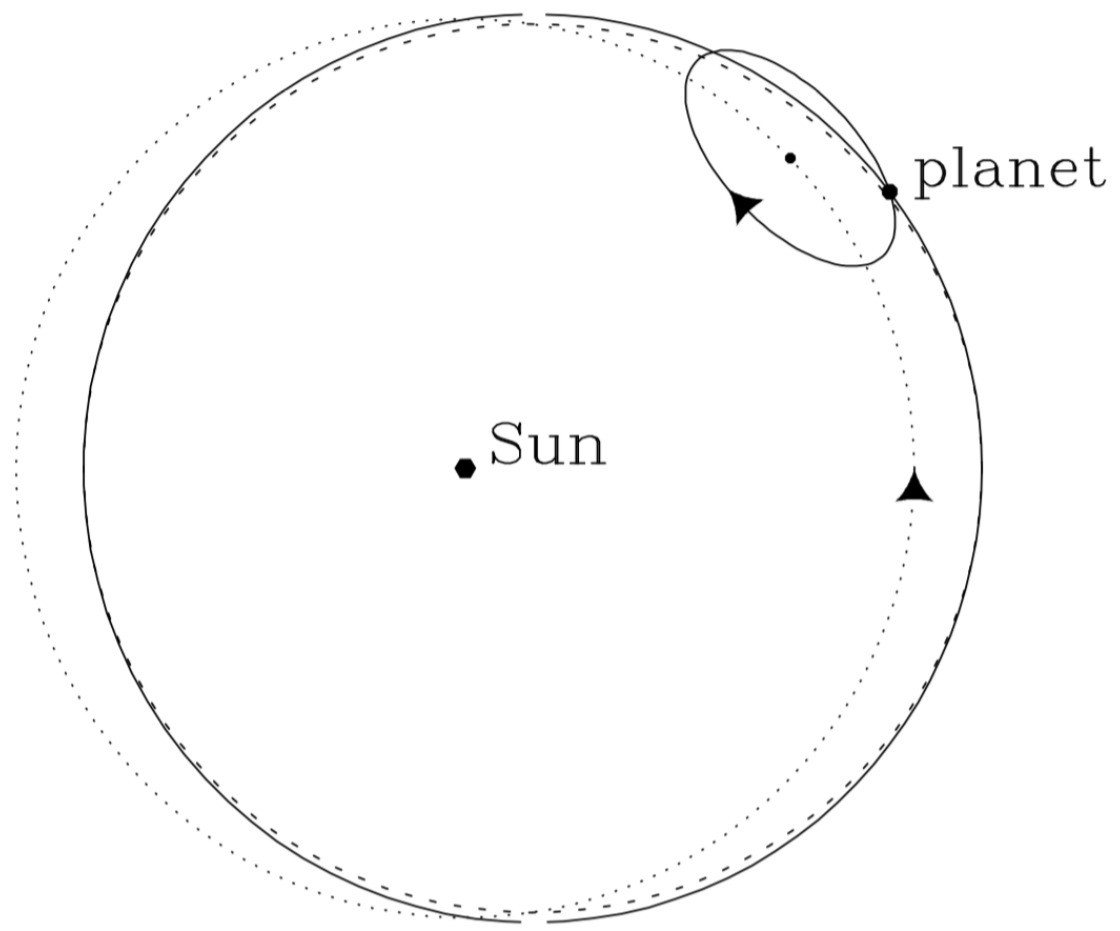
The epicyclic approximation for  
orbits in axisymmetric potentials

BT2, §3.2.3

# Overview

In axisymmetric potentials, nearly circular orbits can be approximated as retrograde elliptical motion with epicyclic frequency  $\kappa$  on top of circular motion of a guiding center with angular frequency  $\Omega$

$$\kappa = \sqrt{d\Omega^2 / d \ln R + 4\Omega^2}$$



# Main steps of the epicyclic approximation derivation

- ▶ Write general EOMs in cylindrical coordinates
- ▶ Specialize to axisymmetric case and define effective potential  $\Phi_{\text{eff}}$ , such that  $R, z$  EOMs look like Cartesian EOMs in  $\Phi_{\text{eff}}$
- ▶ Show that  $\Phi_{\text{eff}}$  minimum (guiding center) follows a circular orbit around the center of the system
- ▶ Taylor expand  $\Phi_{\text{eff}}$  around its minimum and show that motion in  $(x, y, z)$  coordinates in the frame of the guiding center can be approximated as simple harmonic oscillations with frequencies  $\kappa$  (in  $x, y$ ) and  $\nu$  (in  $z$ )
- ▶ Derive expression for  $\kappa$  in terms of the  $\Omega$  profile of the system
- ▶ Obtain explicit solutions for  $(x(t), y(t), z(t))$  elliptic motion

# Gravitational dynamics in cylindrical coordinates

$$\mathbf{r} = R\hat{\mathbf{e}}_R + z\hat{\mathbf{e}}_z$$

$$\mathbf{v} = \dot{R}\hat{\mathbf{e}}_R + R\dot{\phi}\hat{\mathbf{e}}_\phi + \dot{z}\hat{\mathbf{e}}_z$$

$$\mathbf{a} = (\ddot{R} - R\dot{\phi}^2)\hat{\mathbf{e}}_R + (2\dot{R}\dot{\phi} + R\ddot{\phi})\hat{\mathbf{e}}_\phi + \ddot{z}\hat{\mathbf{e}}_z$$

$$\nabla\Phi = \frac{\partial\Phi}{\partial R}\hat{\mathbf{e}}_R + \frac{1}{R}\frac{\partial\Phi}{\partial\phi}\hat{\mathbf{e}}_\phi + \frac{\partial\Phi}{\partial z}\hat{\mathbf{e}}_z$$

Equations of motion:

$$\mathbf{a} = -\nabla\Phi \quad \Rightarrow \quad \left\{ \begin{array}{l} \ddot{R} - R\dot{\phi}^2 = -\frac{\partial\Phi}{\partial R} \\ 2\dot{R}\dot{\phi} + R\ddot{\phi} = \frac{1}{R}\frac{d(R^2\dot{\phi})}{dt} = -\frac{1}{R}\frac{\partial\Phi}{\partial\phi} \\ \ddot{z} = -\frac{\partial\Phi}{\partial z} \end{array} \right.$$

# Axisymmetric case

$$\Phi = \Phi(R, z) \Rightarrow \frac{\partial \Phi}{\partial \phi} = 0 \quad \Rightarrow \quad \frac{d(R^2 \dot{\phi})}{dt} = 0$$

$$\Rightarrow L_z = R^2 \dot{\phi} = \text{const.}$$

$z$  component  
of angular  
momentum

$$\Rightarrow \dot{\phi} = \frac{L_z}{R^2}$$

Reformulate  $R, z$  EOMs  
using this result:

$$\ddot{R} = -\frac{\partial \Phi}{\partial R} + \frac{L_z^2}{R^3} = -\frac{\partial \Phi_{\text{eff}}}{\partial R}$$

$$\ddot{z} = -\frac{\partial \Phi_{\text{eff}}}{\partial z}, \text{ where } \Phi_{\text{eff}} \equiv \Phi + \frac{L_z^2}{2R^2}$$

I.e., motion in  $R, z$  modeled as oscillations in effective potential  $\Phi_{\text{eff}}$

Coordinates of the guiding center =  $\Phi_{\text{eff}}$  minimum

Coordinates  $(R_g, \phi_g, z_g)$  of the  $\Phi_{\text{eff}}$  minimum satisfy:

$$0 = \frac{\partial \Phi_{\text{eff}}}{\partial R} = \frac{\partial \Phi}{\partial R} - \frac{L_z^2}{R^3}$$

$$0 = \frac{\partial \Phi_{\text{eff}}}{\partial z}$$

Assume that  $\Phi$  is symmetric about  $z$ . Then the last equation is true everywhere in  $z=0$  plane and the first holds in that plane where

$$\left( \frac{\partial \Phi}{\partial R} \right)_{(R_g, 0)} = \frac{L_z^2}{R_g^3} = R_g \dot{\phi}_g^2 \quad \text{centripetal acceleration of circular orbit of radius } R_g$$

I.e.,  $R, z$  oscillate about circular orbit of radius  $R_g$  and angular momentum  $L_z$

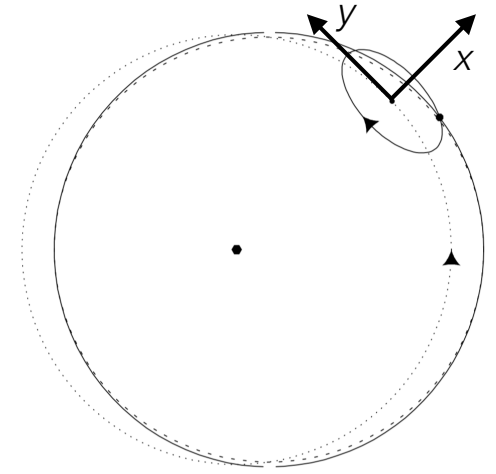
# EOMs relative to guiding center

For small  $x \equiv R - R_g$ ,

0 (can add arbitrary const.)

0 ( $(R_g, 0)$  is  $\Phi_{\text{eff}}$  minimum)

$$\Phi_{\text{eff}} = \Phi_{\text{eff}}(R_g, 0) + \frac{\partial \Phi_{\text{eff}}}{\partial R} \Big|_{(R_g, 0)} x + \frac{\partial \Phi_{\text{eff}}}{\partial z} \Big|_{(R_g, 0)} z + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial R^2} \Big|_{(R_g, 0)} x^2 + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial z^2} \Big|_{(R_g, 0)} z^2 + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial x \partial z} \Big|_{(R_g, 0)} xz + \dots$$



0 ( $\Phi_{\text{eff}}$  symmetric about  $z=0$ )

In Cartesian  $(x, z)$  frame,

$$\mathbf{a} = -\nabla \Phi_{\text{eff}}$$

$$\ddot{x} = -\frac{\partial \Phi_{\text{eff}}}{\partial x} \approx -\frac{\partial^2 \Phi_{\text{eff}}}{\partial R^2} \Big|_{(R_g, 0)} x \equiv -\kappa^2 x$$

$$\ddot{z} = -\frac{\partial \Phi_{\text{eff}}}{\partial z} \approx -\frac{\partial^2 \Phi_{\text{eff}}}{\partial z^2} \Big|_{(R_g, 0)} z \equiv -\nu^2 z$$

Harmonic oscillators with frequencies  $\kappa$  and  $\nu$

# How to compute epicyclic frequency

Using definition  $\Phi_{\text{eff}} = \Phi + \frac{L_z^2}{2R^2}$ ,  $\kappa^2 = \left( \frac{\partial^2 \Phi}{\partial R^2} \right)_{(R_g, 0)} + \frac{3L_z}{R_g^4}$

Circular angular frequency:  $\Omega^2 = \frac{1}{R} \left( \frac{\partial \Phi}{\partial R} \right)_{(R_g, 0)} = \frac{L_z^2}{R^4}$

(since for circular orbit

$$\partial \Phi / \partial R = R \dot{\phi}^2; \quad \Omega = \dot{\phi})$$

$$\begin{aligned} \Rightarrow \kappa^2(R_g) &= \left( \Omega^2 + R \frac{d\Omega^2}{dR} + 3\Omega^2 \right)_{R_g} = \left( R \frac{d\Omega^2}{dR} + 4\Omega^2 \right)_{R_g} \\ &= \frac{\partial^2 \Phi / \partial R^2}{3L_z / R_g^4} = \left( \frac{d\Omega^2}{d \ln R} + 4\Omega^2 \right)_{R_g} \end{aligned}$$

# Elliptic motion around guiding center

$$\mathbf{x}: \ddot{x} = -\kappa^2 x \quad \Rightarrow \quad x(t) = X \cos(\kappa t + \alpha) \quad \text{for } X \geq 0 \text{ and } \alpha \text{ constant}$$

$$\mathbf{y}: \dot{\phi} = \frac{L_z}{R^2} \quad L_z = \text{const. in axisymmetric potential}$$

$$= \frac{L_z}{R_g^2} \left(1 + \frac{x}{R_g}\right)^{-2} \quad R = R_g + x = R_g(1 + x/R_g)$$

$$\approx \frac{L_z}{R_g^2} \left(1 - \frac{2x}{R_g}\right) \quad \text{Taylor expansion}$$

$$\Rightarrow \phi = \Omega_g t - \frac{2\Omega_g X}{R_g \kappa} \sin(\kappa t + \alpha) + \phi_0 \quad \text{integrating}$$

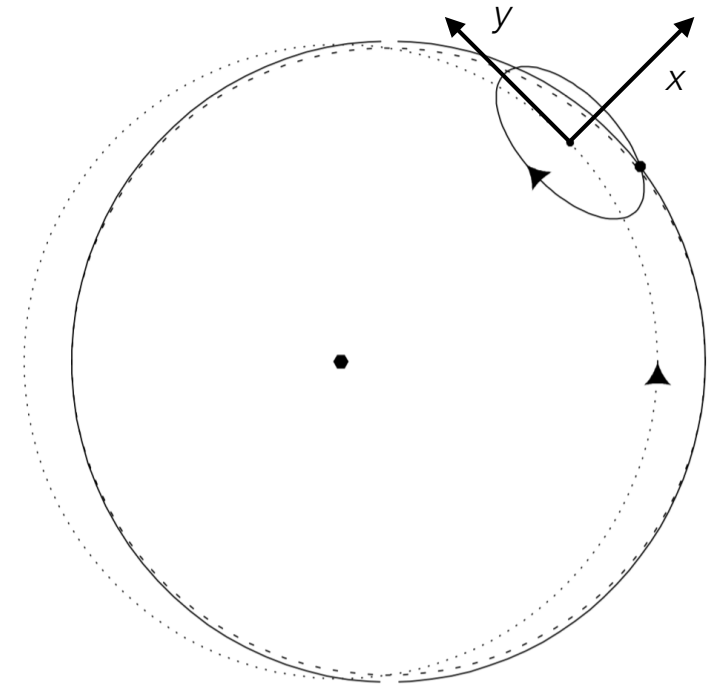
$$y \approx R_g(\phi - \phi_g) = -\frac{2\Omega_g X}{\kappa} \sin(\kappa t + \alpha) \equiv -Y \sin(\kappa t + \alpha)$$

# Summary of epicyclic motion

$$x = X \cos(\kappa t + \alpha)$$

$$y = -Y \sin(\kappa t + \alpha)$$

$$z = Z \cos(\nu t + \xi) \quad \text{similarly as for } x$$



Elliptic motion in  $xy$  plane with aspect ratio  $\frac{X}{Y} = \frac{\kappa}{2\Omega_g}$

Motion around the around the epicycle is opposite in sense to the rotation of of the guiding center. Conservation of  $L_z = R^2 \dot{\phi} \Rightarrow \dot{\phi}$  decreases when  $R$  increases