# Robotics Level 1 Syllabus

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<tr>
<th>Session</th>
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| Session 1 | Getting started with Robotics / VexVR | Rules for the Class  
Ice Breaker  
TA Introductions  
Distance Drive Challenge  
Standard Drive Base |
| Session 2 | VexVR: Loops, Looks, Drivetrain | Ice Breaker  
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Standard Drive Base  
Driver Precision |
| Session 3 | VexVR: Using sensors and learning to use the Clawbot arm | Icebreakers  
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Clawbot  
Clawbot Precision |
| Session 4 | VexVR: Creating algorithms and loops | Icebreakers  
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| Session 5 | Color Sensors and Disassembling | Ice Breakers  
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Disassembling |