

Long time dispersive estimates for perturbations of a kink solution of one dimensional cubic wave equations

Jean-Marc Delort

Université Sorbonne Paris-Nord
(Joint work with Nader Masmoudi)

1. Motivations

Goal: Stability of stationary solution H of a nonlinear wave equation (in dimension 1).

Example: • $H \equiv 0$ stationary solution of $(\partial_t^2 - \partial_x^2 + 1)u = N(u) = O(u^2)$, $u \rightarrow 0$. If Cauchy data are of size $\epsilon \ll 1$ in a space of smooth decaying functions, then $\|u(t, \cdot)\|_{L^\infty} = O(\epsilon t^{-\frac{1}{2}})$, $t \rightarrow +\infty$ (Lindblad-Soffer, D., Stingo).

• The *kink* $H(x) = \tanh(x/\sqrt{2})$ is a stationary solution of the ϕ^4 model

$$(\partial_t^2 - \partial_x^2)\phi = \phi - \phi^3.$$

Write $\phi(t, x) = H(x) + \varphi(t\sqrt{2}, x\sqrt{2})$. Then the perturbation φ solves

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3$$

where

$$D_t = \frac{1}{i}\partial_t, V(x) = -\frac{3}{4}\cosh^{-2}\left(\frac{x}{2}\right) \in \mathcal{S}(\mathbb{R}), \kappa(x) = \frac{3}{2}\tanh\left(\frac{x}{2}\right).$$

Known results • Orbital stability of H (Henry, Perez and Wreszinski).

1. Motivations

Goal: Stability of stationary solution H of a nonlinear wave equation (in dimension 1).

Example: • $H \equiv 0$ stationary solution of

$(\partial_t^2 - \partial_x^2 + 1)u = N(u) = O(u^2)$, $u \rightarrow 0$. If Cauchy data are of size $\epsilon \ll 1$ in a space of smooth decaying functions, then

$\|u(t, \cdot)\|_{L^\infty} = O(\epsilon t^{-\frac{1}{2}})$, $t \rightarrow +\infty$ (Lindblad-Soffer, D., Stingo).

• The *kink* $H(x) = \tanh(x/\sqrt{2})$ is a stationary solution of the ϕ^4 model

$$(\partial_t^2 - \partial_x^2)\phi = \phi - \phi^3.$$

Write $\phi(t, x) = H(x) + \varphi(t\sqrt{2}, x\sqrt{2})$. Then the perturbation φ solves

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3$$

where

$$D_t = \frac{1}{i}\partial_t, V(x) = -\frac{3}{4}\cosh^{-2}\left(\frac{x}{2}\right) \in \mathcal{S}(\mathbb{R}), \kappa(x) = \frac{3}{2}\tanh\left(\frac{x}{2}\right).$$

Known results • Orbital stability of H (Henry, Perez and Wreszinski).

1. Motivations

Goal: Stability of stationary solution H of a nonlinear wave equation (in dimension 1).

Example: • $H \equiv 0$ stationary solution of

$(\partial_t^2 - \partial_x^2 + 1)u = N(u) = O(u^2)$, $u \rightarrow 0$. If Cauchy data are of size $\epsilon \ll 1$ in a space of smooth decaying functions, then

$\|u(t, \cdot)\|_{L^\infty} = O(\epsilon t^{-\frac{1}{2}})$, $t \rightarrow +\infty$ (Lindblad-Soffer, D., Stingo).

• The *kink* $H(x) = \tanh(x/\sqrt{2})$ is a stationary solution of the ϕ^4 model

$$(\partial_t^2 - \partial_x^2)\phi = \phi - \phi^3.$$

Write $\phi(t, x) = H(x) + \varphi(t\sqrt{2}, x\sqrt{2})$. Then the perturbation φ solves

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3$$

where

$$D_t = \frac{1}{i}\partial_t, V(x) = -\frac{3}{4}\cosh^{-2}\left(\frac{x}{2}\right) \in \mathcal{S}(\mathbb{R}), \kappa(x) = \frac{3}{2}\tanh\left(\frac{x}{2}\right).$$

Known results • Orbital stability of H (Henry, Perez and Wreszinski).

- Kowalczyk, Martel and Muñoz: Asymptotic stability locally in space.

Operator $-\partial_x^2 + 2V(x)$ has $[0, +\infty[$ as absolutely continuous spectrum and two eigenvalues -1 and $-\frac{1}{4}$.

Restriction: From now on we consider only **odd** perturbations φ . Then if Y is a normalized eigenfunction associated to eigenvalue $-\frac{1}{4}$, we may decompose

$$(\varphi(t, x), \partial_t \varphi(t, x)) = \underbrace{(u_1(t, x), u_2(t, x))}_{\text{Proj. on a.c. spectrum}} + (z_1(t), z_2(t)) Y(x).$$

Theorem (KMM)

If $(\varphi, \partial_t \varphi)|_{t=0}$ is small in $H^1 \times L^2$ and odd, then

$$\int_{-\infty}^{+\infty} [|z_1(t)|^4 + |z_2(t)|^4] dt < +\infty$$

$$\int_{-\infty}^{+\infty} \int_{\mathbb{R}} [(\partial_x u_1)^2 + u_1^2 + u_2^2](t, x) e^{-c_0|x|} dx dt < +\infty.$$

- Kowalczyk, Martel and Muñoz: Asymptotic stability locally in space.

Operator $-\partial_x^2 + 2V(x)$ has $[0, +\infty[$ as absolutely continuous spectrum and two eigenvalues -1 and $-\frac{1}{4}$.

Restriction: From now on we consider only **odd** perturbations φ . Then if Y is a normalized eigenfunction associated to eigenvalue $-\frac{1}{4}$, we may decompose

$$(\varphi(t, x), \partial_t \varphi(t, x)) = \underbrace{(u_1(t, x), u_2(t, x))}_{\text{Proj. on a.c. spectrum}} + (z_1(t), z_2(t)) Y(x).$$

Theorem (KMM)

If $(\varphi, \partial_t \varphi)|_{t=0}$ is small in $H^1 \times L^2$ and odd, then

$$\int_{-\infty}^{+\infty} [|z_1(t)|^4 + |z_2(t)|^4] dt < +\infty$$

$$\int_{-\infty}^{+\infty} \int_{\mathbb{R}} [(\partial_x u_1)^2 + u_1^2 + u_2^2](t, x) e^{-c_0|x|} dx dt < +\infty.$$

- Kowalczyk, Martel and Muñoz: Asymptotic stability locally in space.

Operator $-\partial_x^2 + 2V(x)$ has $[0, +\infty[$ as absolutely continuous spectrum and two eigenvalues -1 and $-\frac{1}{4}$.

Restriction: From now on we consider only **odd** perturbations φ . Then if Y is a normalized eigenfunction associated to eigenvalue $-\frac{1}{4}$, we may decompose

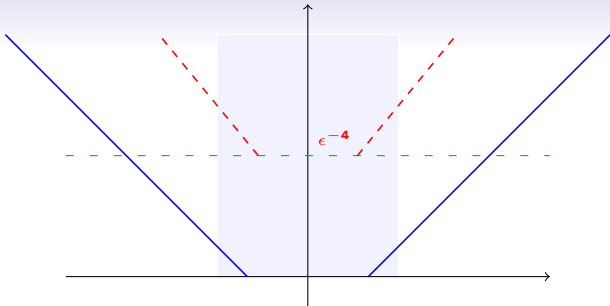
$$(\varphi(t, x), \partial_t \varphi(t, x)) = \underbrace{(u_1(t, x), u_2(t, x))}_{\text{Proj. on a.c. spectrum}} + (z_1(t), z_2(t)) Y(x).$$

Theorem (KMM)

If $(\varphi, \partial_t \varphi)|_{t=0}$ is small in $H^1 \times L^2$ and odd, then

$$\int_{-\infty}^{+\infty} [|z_1(t)|^4 + |z_2(t)|^4] dt < +\infty$$

$$\int_{-\infty}^{+\infty} \int_{\mathbb{R}} [(\partial_x u_1)^2 + u_1^2 + u_2^2](t, x) e^{-\epsilon_0 |x|} dx dt < +\infty.$$



Theorem (KMM)

If $(\varphi, \partial_t \varphi)|_{t=0}$ is small in $H^1 \times L^2$ and odd, then

$$\int_{-\infty}^{+\infty} [|z_1(t)|^4 + |z_2(t)|^4] dt < +\infty$$

$$\int_{-\infty}^{+\infty} \int_{\mathbb{R}} [(\partial_x u_1)^2 + u_1^2 + u_2^2](t, x) e^{-c_0|x|} dx dt < +\infty.$$

2. Statement of main theorem

Recall that the (odd) perturbation φ solves

$$(E) \quad (D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3.$$

We decompose $\varphi = P_{ac}\varphi + a(t)Y$, with P_{ac} = spectral projector on a.c. spectrum and $a(t) = \langle \varphi, Y \rangle$. One gets

$$(S) \quad \begin{aligned} \left(D_t^2 - \frac{3}{4}\right)a(t) &= \langle \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3, Y \rangle \\ (D_t^2 - (D_x^2 + 1 + 2V(x)))(P_{ac}\varphi) &= P_{ac}(\kappa(x)\varphi^2 + \frac{1}{2}\varphi^3). \end{aligned}$$

We want to solve (E) or (S) with initial data at $t = 1$, that are smooth enough, decaying and small i.e. that will be of the form $\varphi|_{t=1} = \epsilon\varphi_0, \partial_t\varphi|_{t=1} = \epsilon\varphi_1$ with

$$\|\varphi_0\|_{H^{s+1}} + \|\varphi_1\|_{H^s} + \|x\varphi_0\|_{H^1} + \|x\varphi_1\|_{L^2} \leq 1,$$

with $\epsilon \ll 1$ and s large enough.

Theorem

There is $\rho_0 \in \mathbb{N}$ and for any $\rho \geq \rho_0$, any $c > 0$, any $\theta' \in]0, \frac{1}{2}[$, any large enough N, s , there are $\epsilon_0 > 0, C > 0$ such that the solution to (S) with odd initial data of size $\epsilon < \epsilon_0$ is defined for $t \in [1, \epsilon^{-4+c}[$ and one has the estimates

$$a(t) = \langle Y, \varphi \rangle = e^{it\frac{\sqrt{3}}{2}} g_+(t) - e^{-it\frac{\sqrt{3}}{2}} g_-(t)$$

$$|g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}}, \quad |\partial_t g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}} t^{-\frac{1}{2}}$$

$$\|P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{1}{2}} (\epsilon^2 \sqrt{t})^{\theta'}$$

$$\|\langle x \rangle^{-2N} D_t^j P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{3}{4}} (\epsilon^2 \sqrt{t})^{\theta'}, \quad j = 0, 1.$$

Theorem

There is $\rho_0 \in \mathbb{N}$ and for any $\rho \geq \rho_0$, any $c > 0$, any $\theta' \in]0, \frac{1}{2}[$, any large enough N, s , there are $\epsilon_0 > 0, C > 0$ such that the solution to (S) with odd initial data of size $\epsilon < \epsilon_0$ is defined for $t \in [1, \epsilon^{-4+c}[$ and one has the estimates

$$a(t) = \langle Y, \varphi \rangle = e^{it\frac{\sqrt{3}}{2}} g_+(t) - e^{-it\frac{\sqrt{3}}{2}} g_-(t)$$

$$|g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}}, \quad |\partial_t g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}} t^{-\frac{1}{2}}$$

$$\|P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{1}{2}} (\epsilon^2 \sqrt{t})^{\theta'}$$

$$\|\langle x \rangle^{-2N} D_t^j P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{3}{4}} (\epsilon^2 \sqrt{t})^{\theta'}, \quad j = 0, 1.$$

Remarks: • For an equation $(D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = NL(x, \varphi)$ and a potential *without bound states*, Germain and Pusateri prove a $O(\epsilon t^{-\frac{1}{2}})$ L^∞ bound.

Theorem

There is $\rho_0 \in \mathbb{N}$ and for any $\rho \geq \rho_0$, any $c > 0$, any $\theta' \in]0, \frac{1}{2}[$, any large enough N, s , there are $\epsilon_0 > 0, C > 0$ such that the solution to (S) with odd initial data of size $\epsilon < \epsilon_0$ is defined for $t \in [1, \epsilon^{-4+c}[$ and one has the estimates

$$a(t) = \langle Y, \varphi \rangle = e^{it\frac{\sqrt{3}}{2}} g_+(t) - e^{-it\frac{\sqrt{3}}{2}} g_-(t)$$

$$|g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}}, \quad |\partial_t g_{\pm}(t)| \leq \frac{C\epsilon}{\sqrt{1+t\epsilon^2}} t^{-\frac{1}{2}}$$

$$\|P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{1}{2}} (\epsilon^2 \sqrt{t})^{\theta'}$$

$$\|\langle x \rangle^{-2N} D_t^j P_{ac}\varphi(t, \cdot)\|_{W^{\rho, \infty}} \leq Ct^{-\frac{3}{4}} (\epsilon^2 \sqrt{t})^{\theta'}, \quad j = 0, 1.$$

Remarks: • If $t \gg \epsilon^{-4}$, possible logarithmic loss

$\|P_{ac}\varphi(t, \cdot)\|_{L^\infty} = O\left(\frac{\log t}{\sqrt{t}}\right)$. See Lindblad, Lührmann and Soffer for

$(D_t^2 - (D_x^2 + 1))\varphi = a(x)\varphi^2 + b(x)\varphi^3$ Lindblad, Lührmann, Soffer and Schlag for $(D_t^2 - (D_x^2 + 1 + 2V(x)))\varphi = P_{ac}(a(\cdot)u^2)$.

• Our bounds imply the integral bounds of KMM (up to time ϵ^{-4}).

3. The case of NLKG

Recall the bootstrap argument for small perturbations of the zero solution of NLKG i.e. small solutions to $(D_t - \rho(D_x))u = |u|^2 u$, with $\rho(\xi) = \sqrt{1 + \xi^2}$. If $L_+ = x + t\rho'(D_x)$, one gets the optimal dispersive estimates proving the set of inequalities

$$(E_A) \quad \begin{aligned} \|u(t, \cdot)\|_{H^s} &\leq A\epsilon t^\delta \\ \|L_+ u(t, \cdot)\|_{L^2} &\leq A\epsilon t^\delta \\ \|u(t, \cdot)\|_{L^\infty} &\leq \frac{A\epsilon}{\sqrt{t}}. \end{aligned}$$

Bootstrap: Assume (E_A) with $0 < \delta \ll 1, s \gg 1, \epsilon \ll 1, A \gg 1$ on $[1, T]$. Using the equation, show that then $(E_{A/2})$ holds on $[1, T]$.

Idea of proof to show the second inequality in $(E_{A/2})$: Use that $[L_+, D_t - \rho(D_x)] = 0$ to write

$$(D_t - \rho(D_x))(L_+ u) = L_+ (|u|^2 u) = O_{L^2}(\|u\|_{L^\infty}^2 \|L_+ u\|_{L^2}).$$

Apply energy inequality to get second in equality in $(E_{A/2})$.

3. The case of NLKG

Recall the bootstrap argument for small perturbations of the zero solution of NLKG i.e. small solutions to $(D_t - \rho(D_x))u = |u|^2 u$, with $\rho(\xi) = \sqrt{1 + \xi^2}$. If $L_+ = x + t\rho'(D_x)$, one gets the optimal dispersive estimates proving the set of inequalities

$$(E_A) \quad \begin{aligned} \|u(t, \cdot)\|_{H^s} &\leq A\epsilon t^\delta \\ \|L_+ u(t, \cdot)\|_{L^2} &\leq A\epsilon t^\delta \\ \|u(t, \cdot)\|_{L^\infty} &\leq \frac{A\epsilon}{\sqrt{t}}. \end{aligned}$$

Bootstrap: Assume (E_A) with $0 < \delta \ll 1, s \gg 1, \epsilon \ll 1, A \gg 1$ on $[1, T]$. Using the equation, show that then $(E_{A/2})$ holds on $[1, T]$.

Idea of proof to show the second inequality in $(E_{A/2})$: Use that $[L_+, D_t - \rho(D_x)] = 0$ to write

$$(D_t - \rho(D_x))(L_+ u) = L_+ (|u|^2 u) = O_{L^2}(\|u\|_{L^\infty}^2 \|L_+ u\|_{L^2}).$$

Apply energy inequality to get second in equality in $(E_{A/2})$.

4. Some ideas of proof

The equation satisfied by $P_{ac}\varphi$ is

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))(P_{ac}\varphi) = P_{ac}(\text{Non linearity}).$$

Idea: Reduce that equation to $(D_t - p(D_x))u = |u|^2 u$.

1st Step: Conjugation through wave operators.

Define $A = -\frac{1}{2}\partial_x^2 + V(x)$, $A_0 = -\frac{1}{2}\partial_x^2$,

$W_+ = s - \lim_{t \rightarrow +\infty} e^{itA} e^{-itA_0}$. Then one knows that

$W_+^*[D_x^2 + 2V(x)]P_{ac} = D_x^2 W_+^* P_{ac}$. Setting $w = W_+^* P_{ac}\varphi$, this implies

$$(D_t^2 - (D_x^2 + 1))w = b(x, D_x)^* [\kappa(x)[a(t)Y + b(x, D_x)w]^2 + \frac{1}{2}b(x, D_x)^* [(a(t)Y + b(x, D_x)w)^3]$$

where $b(x, \xi)$ is a pseudo-differential symbol of order zero with $\frac{\partial b}{\partial x}(x, \xi) = O(\langle x \rangle^{-\infty})$, $x \rightarrow \pm\infty$.

Setting $u_{\pm} = (D_t \pm p(D_x))w$, one may rewrite this second order equation as a first order system.

4. Some ideas of proof

The equation satisfied by $P_{ac}\varphi$ is

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))(P_{ac}\varphi) = P_{ac}(\text{Non linearity}).$$

Idea: Reduce that equation to $(D_t - p(D_x))u = |u|^2 u$.

1st Step: *Conjugation through wave operators.*

Define $A = -\frac{1}{2}\partial_x^2 + V(x)$, $A_0 = -\frac{1}{2}\partial_x^2$,

$W_+ = s - \lim_{t \rightarrow +\infty} e^{itA} e^{-itA_0}$. Then one knows that

$W_+^*[D_x^2 + 2V(x)]P_{ac} = D_x^2 W_+^* P_{ac}$. Setting $w = W_+^* P_{ac}\varphi$, this implies

$$(D_t^2 - (D_x^2 + 1))w = b(x, D_x)^* [\kappa(x)[a(t)Y + b(x, D_x)w]^2 + \frac{1}{2}b(x, D_x)^* [(a(t)Y + b(x, D_x)w)^3]$$

where $b(x, \xi)$ is a pseudo-differential symbol of order zero with $\frac{\partial b}{\partial x}(x, \xi) = O(\langle x \rangle^{-\infty})$, $x \rightarrow \pm\infty$.

Setting $u_{\pm} = (D_t \pm p(D_x))w$, one may rewrite this second order equation as a first order system.

4. Some ideas of proof

The equation satisfied by $P_{ac}\varphi$ is

$$(D_t^2 - (D_x^2 + 1 + 2V(x)))(P_{ac}\varphi) = P_{ac}(\text{Non linearity}).$$

Idea: Reduce that equation to $(D_t - p(D_x))u = |u|^2 u$.

1st Step: *Conjugation through wave operators.*

Define $A = -\frac{1}{2}\partial_x^2 + V(x)$, $A_0 = -\frac{1}{2}\partial_x^2$,

$W_+ = s - \lim_{t \rightarrow +\infty} e^{itA} e^{-itA_0}$. Then one knows that

$W_+^*[D_x^2 + 2V(x)]P_{ac} = D_x^2 W_+^* P_{ac}$. Setting $w = W_+^* P_{ac}\varphi$, this implies

$$(D_t^2 - (D_x^2 + 1))w = b(x, D_x)^* [\kappa(x)[a(t)Y + b(x, D_x)w]^2 + \frac{1}{2}b(x, D_x)^* [(a(t)Y + b(x, D_x)w)^3]$$

where $b(x, \xi)$ is a pseudo-differential symbol of order zero with $\frac{\partial b}{\partial x}(x, \xi) = O(\langle x \rangle^{-\infty})$, $x \rightarrow \pm\infty$.

Setting $u_{\pm} = (D_t \pm p(D_x))w$, one may rewrite this second order equation as a first order system.

Step 2: Elimination of quadratic terms by normal form.

Equation on the unknown u_+ :

$$\begin{aligned}(D_t - p(D_x))u_+ &= a(t)^2 \underbrace{Y_2}_{\in \mathcal{S}(\mathbb{R})} + a(t)^3 \underbrace{Y_3}_{\in \mathcal{S}(\mathbb{R})} \\ &+ a(t) \underbrace{Q'_1(x, u_+, \bar{u}_+)}_{\text{linear in } (u_+, \bar{u}_+) \text{ with coeff. in } \mathcal{S}(\mathbb{R})} \\ &+ \underbrace{Q_2(x, u_+, \bar{u}_+)}_{\text{quadratic in } (u_+, \bar{u}_+) \text{ with coeff. with derivative in } \mathcal{S}(\mathbb{R})} \\ &+ \underbrace{Q_3(x, u_+, \bar{u}_+)}_{\text{cubic in } (u_+, \bar{u}_+) \text{ with coeff. with derivative in } \mathcal{S}(\mathbb{R})}.\end{aligned}$$

The worst term above is Q_2 . One eliminates it through a “time normal form” à la Shatah, finding a new quadr. form \tilde{Q}_2 such that

$$\begin{aligned}(D_t - p(D_x))[u_+ - \tilde{Q}_2(x, u_+, \bar{u}_+)] \\ = \text{same terms as above except that } Q_2 \text{ is replaced by } Q'_2\end{aligned}$$

where $Q'_2(x, u_+, \bar{u}_+)$ is still quadratic, but with coefficients in $\mathcal{S}(\mathbb{R})$.

Step 2: *Elimination of quadratic terms by normal form.*

Equation on the unknown u_+ :

$$\begin{aligned}
 (D_t - p(D_x))u_+ &= a(t)^2 \underbrace{Y_2}_{\in \mathcal{S}(\mathbb{R})} + a(t)^3 \underbrace{Y_3}_{\in \mathcal{S}(\mathbb{R})} \\
 &+ a(t) \underbrace{Q'_1(x, u_+, \bar{u}_+)}_{\text{linear in } (u_+, \bar{u}_+) \text{ with coeff. in } \mathcal{S}(\mathbb{R})} \\
 &+ \underbrace{Q_2(x, u_+, \bar{u}_+)}_{\text{quadratic in } (u_+, \bar{u}_+) \text{ with coeff. with derivative in } \mathcal{S}(\mathbb{R})} \\
 &+ \underbrace{Q_3(x, u_+, \bar{u}_+)}_{\text{cubic in } (u_+, \bar{u}_+) \text{ with coeff. with derivative in } \mathcal{S}(\mathbb{R})}.
 \end{aligned}$$

The worst term above is Q_2 . One eliminates it through a “time normal form” à la Shatah, finding a new quadr. form \tilde{Q}_2 such that

$$\begin{aligned}
 (D_t - p(D_x))[u_+ - \tilde{Q}_2(x, u_+, \bar{u}_+)] \\
 = \text{same terms as above except that } Q_2 \text{ is replaced by } Q'_2
 \end{aligned}$$

where $Q'_2(x, u_+, \bar{u}_+)$ is still quadratic, but with coefficients in $\mathcal{S}(\mathbb{R})$.

Step 2: *Elimination of quadratic terms by normal form.*

Equation on the unknown u_+ :

$$\begin{aligned}
 (D_t - p(D_x))[u_+ - \tilde{Q}_2(x, u_+, \bar{u}_+)] &= a(t)^2 \underbrace{Y_2}_{\in \mathcal{S}(\mathbb{R})} + a(t)^3 \underbrace{Y_3}_{\in \mathcal{S}(\mathbb{R})} \\
 &+ a(t) \underbrace{Q'_1(x, u_+, \bar{u}_+)}_{\text{linear in } (u_+, \bar{u}_+) \text{ with coeff. in } \mathcal{S}(\mathbb{R})} \\
 &+ \underbrace{Q'_2(x, u_+, \bar{u}_+)}_{\text{quadratic in } (u_+, \bar{u}_+) \text{ with coeff. in } \mathcal{S}(\mathbb{R})} \\
 &+ \underbrace{Q_3(x, u_+, \bar{u}_+)}_{\text{cubic in } (u_+, \bar{u}_+) \text{ with coeff. with derivative in } \mathcal{S}(\mathbb{R})}.
 \end{aligned}$$

The worst term above is Q_2 . One eliminates it through a “time normal form” à la Shatah, finding a new quadr. form \tilde{Q}_2 such that

$$\begin{aligned}
 (D_t - p(D_x))[u_+ - \tilde{Q}_2(x, u_+, \bar{u}_+)] \\
 = \text{same terms as above except that } Q_2 \text{ is replaced by } Q'_2
 \end{aligned}$$

where $Q'_2(x, u_+, \bar{u}_+)$ is still quadratic, but with coefficients in $\mathcal{S}(\mathbb{R})$.

Step 3: Elimination of source terms.

Let u^{app} be the solution of the linear equation

$$\begin{aligned}(D_t - \rho(D_x))u^{\text{app}} &= a(t)^2 Y_2 + a(t)^3 Y_3 \\ u^{\text{app}}|_{t=1} &= 0.\end{aligned}$$

Then one gets

$$\begin{aligned}(D_t - \rho(D_x))[u_+ - \tilde{Q}_2(x, u_+, u_-) - u^{\text{app}}] \\ = a(t)Q'_1(x, u_+, \bar{u}_+) + Q'_2(x, u_+, \bar{u}_+) + Q_3(x, u_+, \bar{u}_+).\end{aligned}$$

Proposition

One may decompose $u^{\text{app}} = u_+^{\text{app}} + u_+^{\prime\prime\text{app}} + u_-^{\text{app}} + u_-^{\prime\prime\text{app}}$ with for $t \leq \epsilon^{-4}$

$$\begin{aligned}\|L_+ u_{\pm}^{\text{app}}(t, \cdot)\|_{L^2} &\leq Ct^{\frac{1}{4}}(\epsilon^2 \sqrt{t}) \\ \|L_+ u_{\pm}^{\prime\prime\text{app}}(t, \cdot)\|_{L^\infty} &\leq C \log t \log(1 + \epsilon^2 t) \\ |u_{\pm}^{\text{app}}(t, x)| &\leq C \frac{\epsilon^2 \sqrt{t}}{\sqrt{t}} \left(1 + t^{-\frac{1}{2}} \left|x \pm t \sqrt{\frac{2}{3}}\right|\right)^{-1}\end{aligned}$$

Step 3: Elimination of source terms.

Let u^{app} be the solution of the linear equation

$$\begin{aligned}(D_t - \rho(D_x))u^{\text{app}} &= a(t)^2 Y_2 + a(t)^3 Y_3 \\ u^{\text{app}}|_{t=1} &= 0.\end{aligned}$$

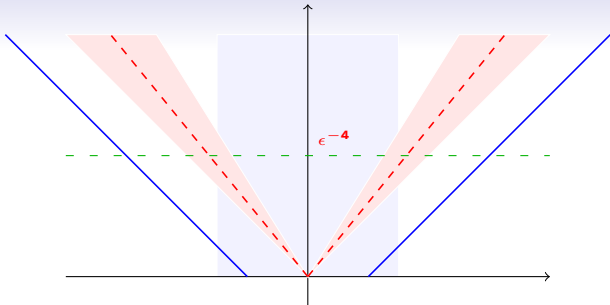
Then one gets

$$\begin{aligned}(D_t - \rho(D_x))[u_+ - \tilde{Q}_2(x, u_+, u_-) - u^{\text{app}}] \\ = a(t)Q'_1(x, u_+, \bar{u}_+) + Q'_2(x, u_+, \bar{u}_+) + Q_3(x, u_+, \bar{u}_+).\end{aligned}$$

Proposition

One may decompose $u^{\text{app}} = u'_+{}^{\text{app}} + u''_+{}^{\text{app}} + u'_-{}^{\text{app}} + u''_-{}^{\text{app}}$ with for $t \leq \epsilon^{-4}$

$$\begin{aligned}\|L_+ u'_\pm{}^{\text{app}}(t, \cdot)\|_{L^2} &\leq Ct^{\frac{1}{4}}(\epsilon^2 \sqrt{t}) \\ \|L_+ u''_\pm{}^{\text{app}}(t, \cdot)\|_{L^\infty} &\leq C \log t \log(1 + \epsilon^2 t) \\ |u'_\pm{}^{\text{app}}(t, x)| &\leq C \frac{\epsilon^2 \sqrt{t}}{\sqrt{t}} \left(1 + t^{-\frac{1}{2}} \left|x \pm t \sqrt{\frac{2}{3}}\right|\right)^{-1}\end{aligned}$$



Proposition

One may decompose $u^{\text{app}} = u_+^{\text{app}} + u_+^{\prime\prime\text{app}} + u_-^{\text{app}} + u_-^{\prime\prime\text{app}}$ with for $t \leq \epsilon^{-4}$

$$\|L_+ u_{\pm}^{\text{app}}(t, \cdot)\|_{L^2} \leq Ct^{\frac{1}{4}}(\epsilon^2 \sqrt{t})$$

$$\|L_+ u_{\pm}^{\prime\prime\text{app}}(t, \cdot)\|_{L^\infty} \leq C \log t \log(1 + \epsilon^2 t)$$

$$|u_{\pm}^{\text{app}}(t, x)| \leq C \frac{\epsilon^2 \sqrt{t}}{\sqrt{t}} \left(1 + t^{-\frac{1}{2}} \left|x \pm t \sqrt{\frac{2}{3}}\right|\right)^{-1}$$

Step 3: Elimination of source terms.

Let u^{app} be the solution of the linear equation

$$\begin{aligned}(D_t - \rho(D_x))u^{\text{app}} &= a(t)^2 Y_2 + a(t)^3 Y_3 \\ u^{\text{app}}|_{t=1} &= 0.\end{aligned}$$

Then one gets

$$\begin{aligned}(D_t - \rho(D_x))\underbrace{[u_+ - \tilde{Q}_2(x, u_+, u_-) - u^{\text{app}}]}_{\tilde{u}_+} \\ = a(t)Q'_1(x, u_+, \bar{u}_+) + Q'_2(x, u_+, \bar{u}_+) + Q_3(x, u_+, \bar{u}_+).\end{aligned}$$

Proposition

One may decompose $u^{\text{app}} = u'_+{}^{\text{app}} + u''_+{}^{\text{app}} + u'_-{}^{\text{app}} + u''_-{}^{\text{app}}$ with for $t \leq \epsilon^{-4}$

$$\begin{aligned}\|L_+ u'_\pm{}^{\text{app}}(t, \cdot)\|_{L^2} &\leq Ct^{\frac{1}{4}}(\epsilon^2 \sqrt{t}) \\ \|L_+ u''_\pm{}^{\text{app}}(t, \cdot)\|_{L^\infty} &\leq C \log t \log(1 + \epsilon^2 t) \\ |u'_\pm{}^{\text{app}}(t, x)| &\leq C \frac{\epsilon^2 \sqrt{t}}{\sqrt{t}} \left(1 + t^{-\frac{1}{2}} \left|x \pm t \sqrt{\frac{2}{3}}\right|\right)^{-1}\end{aligned}$$

Step 4: *Elimination of linear term.*

Set $\tilde{u} = \begin{bmatrix} \tilde{u}_+ \\ \tilde{u}_- \end{bmatrix}$ with $\tilde{u}_- = -\tilde{u}_+$ and define in the same way \tilde{u}^{app} .

Then the preceding equation may be rewritten

$$\begin{aligned}
 (*) \quad & \left(D_t - \begin{bmatrix} p(D_x) & 0 \\ 0 & -p(D_x) \end{bmatrix} - \mathcal{V}(t) \right) \tilde{u} \\
 & = \underbrace{\mathcal{M}_3(\tilde{u}, \tilde{u}^{\text{app}})}_{\text{cubic}} + \underbrace{\mathcal{M}'_2(\tilde{u}, \tilde{u}^{\text{app}})}_{\text{quadratic}}
 \end{aligned}$$

where $\mathcal{V}(t)$ is a matrix of linear operators (whose entries are of the form $b(t, x, D_x)$, with $b(t, x, \xi)$ symbol of order zero, with coefficients rapidly decaying in x). Set $L = \begin{bmatrix} L_+ & 0 \\ 0 & L_- \end{bmatrix}$ with $L_{\pm} = x \pm tp'(D_x)$. Then L does not commute to the $\mathcal{V}(t)$ term in (*). One constructs a “wave operator” $C(t)$ such that

$$C(t) \left(D_t - \begin{bmatrix} p(D_x) & 0 \\ 0 & -p(D_x) \end{bmatrix} - \mathcal{V}(t) \right) = \left(D_t - \begin{bmatrix} p(D_x) & 0 \\ 0 & -p(D_x) \end{bmatrix} \right) C(t).$$

Step 5: *Further step of normal forms and bootstrap.*

The preceding reductions lead to

$$\left(D_t - \begin{bmatrix} p(D_x) & 0 \\ 0 & -p(D_x) \end{bmatrix} \right) C(t)\tilde{u} = C(t)\mathcal{M}_3 + C(t)\mathcal{M}'_2.$$

One performs “space-time normal forms” in order to reduce the cubic term essentially to $\begin{bmatrix} |\tilde{u}_+|^2 \tilde{u}_+ \\ |\tilde{u}_-|^2 \tilde{u}_- \end{bmatrix}$ and to eliminate, up to remainders, the quadratic one. One is then in position to perform a bootstrap argument relying on estimates of the form

$$\begin{aligned} \|\tilde{u}_+(t, \cdot)\|_{H^s} &= O(\epsilon t^\delta) \\ \|L_+ \tilde{u}_+(t, \cdot)\|_{L^2} &= O((\epsilon^2 \sqrt{t})^\theta t^{\frac{1}{4}}) \\ \|\tilde{u}_+(t, \cdot)\|_{L^\infty} &= O\left(\frac{(\epsilon^2 \sqrt{t})^{\theta'}}{\sqrt{t}}\right). \end{aligned}$$

The second estimate is obtained commuting L_+ to the equation. The last one follows deducing from the PDE an ODE.

Step 5: *Further step of normal forms and bootstrap.*

The preceding reductions lead to

$$\left(D_t - \begin{bmatrix} p(D_x) & 0 \\ 0 & -p(D_x) \end{bmatrix} \right) C(t)\tilde{u} = C(t)\mathcal{M}_3 + C(t)\mathcal{M}'_2.$$

One performs “space-time normal forms” in order to reduce the cubic term essentially to $\begin{bmatrix} |\tilde{u}_+|^2 \tilde{u}_+ \\ |\tilde{u}_-|^2 \tilde{u}_- \end{bmatrix}$ and to eliminate, up to remainders, the quadratic one. One is then in position to perform a bootstrap argument relying on estimates of the form

$$\begin{aligned} \|\tilde{u}_+(t, \cdot)\|_{H^s} &= O(\epsilon t^\delta) \\ \|L_+ \tilde{u}_+(t, \cdot)\|_{L^2} &= O((\epsilon^2 \sqrt{t})^\theta t^{\frac{1}{4}}) \\ \|\tilde{u}_+(t, \cdot)\|_{L^\infty} &= O\left(\frac{(\epsilon^2 \sqrt{t})^{\theta'}}{\sqrt{t}}\right). \end{aligned}$$

The second estimate is obtained commuting L_+ to the equation. The last one follows deducing from the PDE an ODE.

Step 6: *Study of the non dispersive component.*

Recall that we had to study a system made of the coupling between a PDE and an ODE given by:

$$\left(D_t^2 - \frac{3}{4}\right)a(t) = \langle \kappa(x)\varphi^2 + \frac{1}{2}\varphi^3, Y \rangle$$

where $\varphi = P_{ac}\varphi + a(t)Y$. One needs to obtain bounds in $C\epsilon(1 + t\epsilon^2)^{-\frac{1}{2}}$ for a . After normal forms one is reduced to

$$D_t g(t) = \left(\alpha - i\frac{\sqrt{6}}{18} \hat{Y}_2(\sqrt{2})^2\right) |g(t)|^2 g(t) + \text{remainders}$$

where α is real and Y_2 is an explicit function in $\mathcal{S}(\mathbb{R})$. To get a solution defined for any $t \geq 1$, one needs a condition on Y_2 , namely that $\hat{Y}_2(\sqrt{2})^2 < 0$. This is the **Fermi Golden Rule**. It is evident that $\hat{Y}_2(\sqrt{2})$ is purely imaginary, so that the condition to check reduces to $\hat{Y}_2(\sqrt{2}) \neq 0$. This condition had been checked numerically by Kowalczyk, Martel and Muñoz. Actually, it reduces to the computation of the integral of an explicit function, that may be done by residues.