# Smooth Imploding Solutions for 3D Compressible Fluids

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### Compressible Euler Equations

Non-Isentropic Form

#### Full non-isentropic Euler equations:

$$\begin{split} \partial_t(\rho\;u) + \operatorname{div}\left(\rho u \otimes u + \rho \operatorname{Id}\right) &= 0 & \text{(Conservation of momentum)} \\ \partial_t \rho + \operatorname{div}(\rho u) &= 0 & \text{(Conservation of mass)} \\ \partial_t E + \operatorname{div}\left((\rho + E)u\right) &= 0 & \text{(Conservation of energy)} \end{split}$$

where u is the velocity,  $\rho$ , the density, p, the pressure and E, the energy. Conservation of energy can be replaced by transport of specific entropy  $\partial_t S + u \cdot \nabla S = 0$ . The pressure is

$$p = (\gamma - 1)(E - \frac{1}{2}\rho|u|^2) = \frac{1}{\gamma}\rho^{\gamma}e^{S}$$

for adiabatic exponent  $\gamma > 1$ . The sound speed is given by

$$c = \sqrt{\frac{\gamma P}{\rho}}$$
.

### Shock waves and imploding solutions

- Shock waves: The prototypical singularity for the Euler equations is a shock wave, which occurs when the speed of a disturbance exceeds the local speed of sound. Mathematically, one is interested in both the formation of the shock and the development of the shock.
- Implosions: Implosions involve spherically symmetric solutions that collapse at a point in finite time. Classically, one considers imploding shock waves. Recently, Merle-Raphael-Rodnianski-Szeftel showed there exist smooth imploding solutions.

#### Shock formation results

- Christodoulou '07, Christodoulou-Miao '14: 3D isentropic, irrotational.
- Luk-Speck '18: 2D isentropic, non-trivial vorticity.
- B-Shkoller-Vicol '19: 2D isentropic, azimuthal, non-trivial vorticity + description of self-similar profile.
- B-Shkoller-Vicol '19: 3D isentropic, non-trivial vorticity + description of self-similar profile.
- B-Shkoller-Vicol '20: Full 3D Euler + description of self-similar profile.
- ► Luk-Speck '21: Full 3D Euler, allow non-generic shocks.

Related works: John-Klainerman '84, Klainerman, John '87, Hörmander '87, John '81, Sideris '85, Alinhac '99

### Shock development results

- Lebaud '94: 1D, 2x2 p-system, existence of discontinuous shock (uniqueness follows by T.P. Liu) (cf. Chen-Dong '01, Kong '02 for generalizations)
- Yin '04: Spherically symmetric Euler, existence of weak solution past formation, no uniqueness and no description of weak discontinuities.
- Christodoulou-Lisbach '16: Spherically symmetric isentropic Euler in formation, restricted problem thereafter, not a weak solution to Euler.
- Christodoulou '19: Multi-D, irrotational, isentropic shock development for the restricted problem, not a weak solution to Euler.
- ▶ B-Drivas-Shkoller-Vicol '21: Development for full Euler under azimuthal symmetry satisfying the Rankine-Hugoniot jump conditions, uniqueness, full description of weak discontinuities.

### Implosion results

- Guderley '42: Self-similar imploding shock waves solutions to Euler.
- Merle-Raphael-Rodnianski-Szeftel '19: Smooth imploding self-similar solutions exist from a.e. adiabatic exponent  $\gamma > 1$ .
- Biasi' 21: Detailed numerical description of smooth self-similar imploding solutions.

#### Related work:

Navier-Stokes (Merle et al. '19), NLS via Madelung transform (Merle et al. '19), Euler Poisson (Guo-Hadzic-Jang-Schrecker '21)

### Setup

Isentropic, spherically symmetric Euler

$$\partial_t u + u \partial_R u + rac{1}{\gamma 
ho} \partial_R 
ho^\gamma = 0 \quad ext{and} \quad \partial_t 
ho + rac{1}{R^2} \partial_R (R^2 
ho u) = 0 \, ,$$

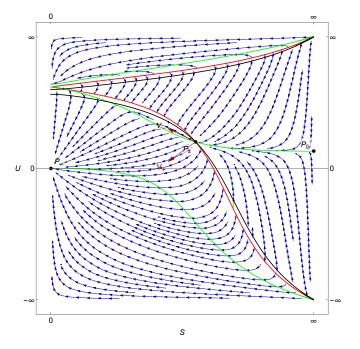
The self-similar ansatz

$$u(r,t) = r^{-1} \frac{R}{T-t} U(\log(\frac{R}{(T-t)^{\frac{1}{r}}})) \text{ and } \sigma(r,t) = \alpha^{-\frac{1}{2}} r^{-1} \frac{R}{T-t} S(\log(\frac{R}{(T-t)^{\frac{1}{r}}})),$$

where  $\sigma = \frac{1}{\alpha} \rho^{\alpha}$  is the rescaled sound speed.

• Setting  $\xi = \log(\frac{R}{(T-t)^{\frac{1}{T}}})$  leads to the autonomous ODE

$$rac{dU}{d\xi} = rac{N_U(U,S)}{D(U,S)}, \quad ext{and} \quad rac{dS}{d\xi} = rac{N_S(U,S)}{D(U,S)} \,.$$



#### Result of Merle et al. '19

For a.e.  $\gamma > 1$ , there exists a countably infinite sequence of self-similar solutions to isentropic Euler. The velocity and density blow up at the origin.

The condition on  $\gamma$  relates to the non-vanishing of an analytic function. The condition is not proven for any specific  $\gamma$ , but may be checked numerically. The case  $\gamma=5/3$  (monatomic gases) is specifically ruled out.

### Compressible Navier-Stokes

#### Isentropic 3D compressible Navier-Stokes with constant viscosity:

$$\partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla p(\rho) - \mu_1 \Delta u - (\mu_1 + \mu_2) \nabla \operatorname{div} u = 0,$$
  
$$\partial_t \rho + \operatorname{div}(\rho u) = 0,$$

for  $\mu_1 \geqslant 0$  and  $2\mu_1 + \mu_2 \geqslant 0$ .

Merle et al. '19: there exists imploding solutions to NS for a.e.  $1 < \gamma < \frac{2+\sqrt{3}}{\sqrt{3}}$  with decaying density.

Previously, Xin '98: blow up for initial data with compact density and Rozanova '08: blow up for rapidly decaying density.

### Problems left open

- 1. Do imploding solutions for Euler exist for all  $\gamma > 1$ ?
- 2. Can one construct imploding solutions to the Navier-Stokes equation with initial density constant at infinity?

#### Main result

- 1. There exists smooth self-similar imploding solutions for all  $\gamma > 1$ .
- 2. For the case  $\gamma = \frac{7}{5}$  (diatomic gas, e.g. oxygen, hydrogen, nitrogen) there exists a countably infinite sequence of imploding solutions.
- 3. Simplified proofs of linear stability and non-linear stability.
- 4. Asymptotically self-similar imploding solutions to NS for  $\gamma = \frac{7}{5}$ .
- 5. First example of initial data with density constant at infinity leading to blow up for NS.

#### Riemann invariants

- ▶ Riemann invariants:  $\mathbf{w} = \mathbf{u} + \mathbf{\sigma}$  and  $\mathbf{z} = \mathbf{u} \mathbf{\sigma}$ .
- Self-similar anzatz

$$w(R, t) = \frac{1}{r} \cdot \frac{R}{T - t} W(\xi)$$
 and  $z(R, t) = \frac{1}{r} \cdot \frac{R}{T - t} Z(\xi)$ 

• Setting  $\xi = \log(\frac{R}{(T-t)^{\frac{1}{r}}})$  yields

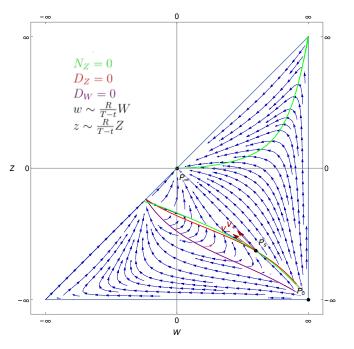
$$(r + \frac{1}{2}((1 + 2\alpha)W + (1 - \alpha)Z))W + (1 + \frac{1}{2}(W + Z + \alpha(W - Z)))\partial_{\xi}W - \frac{\alpha}{2}Z^{2} = 0$$

$$(r + \frac{1}{2}((1 - \alpha)W + (1 + 2\alpha)Z))Z + (1 + \frac{1}{2}(W + Z - \alpha(W - Z)))\partial_{\xi}Z - \frac{\alpha}{2}W^{2} = 0$$

Rearranging,

$$\begin{split} \frac{dW}{d\xi} &= \frac{-(r + \frac{1}{2}((1 + 2\alpha)W + (1 - \alpha)Z))W + \frac{\alpha}{2}Z^2}{1 + \frac{1}{2}(W + Z + \alpha(W - Z))} \\ &= \frac{N_W}{D_W}, \\ \frac{dZ}{d\xi} &= \frac{-(r + \frac{1}{2}((1 - \alpha)W + (1 + 2\alpha)Z))Z + \frac{\alpha}{2}W^2}{1 + \frac{1}{2}(W + Z - \alpha(W - Z))} \\ &= \frac{N_Z}{D_Z}. \end{split}$$





### Analysis of the point $P_s$

Under the change of variables  $\xi \mapsto \psi$  where  $\partial_{\psi} = -D_W D_Z \partial_{\xi}$ :

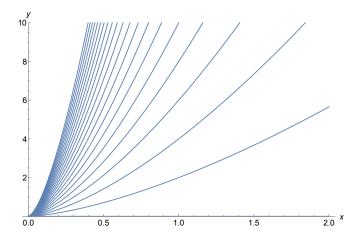
$$\partial_{\psi} W = -N_W D_Z$$
 and  $\partial_{\psi} Z = -N_Z D_W$ ,

 $P_s$  becomes a stable stationary point. Consider the simple ODE:

$$\dot{\mathbf{x}} = \lambda_{+}\mathbf{x}, \quad \dot{\mathbf{y}} = \lambda_{-}\mathbf{y}$$

for  $\lambda_- < \lambda_+ < 0$ . If  $k = \frac{\lambda_-}{\lambda_+} \notin \mathbb{N}$ , x = 0 and y = 0 are the sole smooth solutions. Non-smooth,  $C^k$  solutions exist of the form  $y = Cx^k$  whose series agrees with the solution y = 0 up to order  $\lfloor k \rfloor$ .

## Case $\lambda_- = -\frac{3}{2}$ and $\lambda_+ = -1$



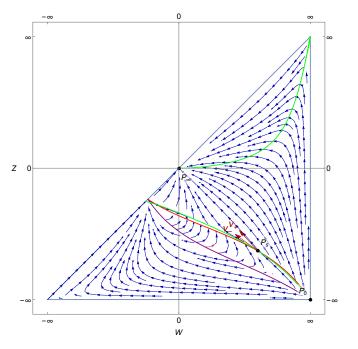
#### Returning to our ODE

$$\partial_{\psi} W = -N_W D_Z$$
 and  $\partial_{\psi} Z = -N_Z D_W$ ,

Let  $\lambda_- < \lambda_+ < 0$  be the eigenvalues of the Jacobian at  $P_s$ , and define

$$k = \frac{\lambda_-}{\lambda_+}$$
.

If  $\nu_-$ ,  $\nu_+$  are the corresponding eigenvectors, we consider smooth solutions tangent to  $\nu_-$ . The smooth solutions tangent to  $\nu_+$  correspond to the Guderley solutions.



### Taylor Expansion around $P_s$ ( $\xi = 0$ )

Write the solution crossing P<sub>s</sub> as a series

$$(\boldsymbol{W}(\xi), \boldsymbol{Z}(\xi) = \sum_{n=0}^{\infty} \frac{\xi^n}{n!} (\boldsymbol{W}_n, \boldsymbol{Z}_n)$$

▶ If  $D_{\circ,n} = \nabla D_{\circ} \cdot (W_n, Z_n)$  for  $\circ \in \{W, Z\}, n \geqslant 1$ , then

$$D_{W,0}W_n = N_{W,n-1} - \sum_{j=0}^{n-2} {n-1 \choose j} D_{W,n-1-j} W_{j+1},$$

$$Z_n D_{Z,1}(n-k) = -\sum_{j=1}^{n-2} {n \choose j} D_{Z,n-j} Z_{j+1} + (N_{Z,n} - (\partial_Z N_Z(P_2)) Z_n) + Z_1 (-D_{Z,n} + Z_n \partial_Z D_Z(P_2)).$$

### The wiggle with r

▶ Restrict 1 < r < r\* where</p>

$$r^*(\gamma) = \begin{cases} \frac{2}{\left(\sqrt{2}\sqrt{\frac{1}{\gamma-1}}+1\right)^2} + 1 & 1 < \gamma < \frac{5}{3}.\\ \frac{3\gamma-1}{2+\sqrt{3}(\gamma-1)} & \gamma \geqslant \frac{5}{3}. \end{cases}$$

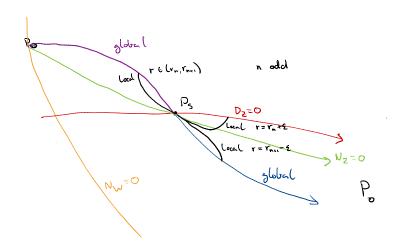
 $k(r): (1, r^*) \to \mathbb{R}$  is increasing with r and  $k \to \infty$  as  $r \to r^*$ .

- ▶ For  $j \in \mathbb{N}$ , define  $r_j$  such that  $j = k(r_j)$ . At  $k_j$  the denominator of  $Z_n$  is singular and switches sign.
- ▶ To connect  $P_0$  to  $P_\infty$ , we show that for n odd
  - 1. For  $r \in (r_n, r_{n+1})$  the solution to the left of  $P_c$  converges to  $P_\infty$  as  $\xi \to \infty$ .
  - 2. For  $r = r_n + \varepsilon$  the solution to the right of  $P_c$  intersects the line  $D_W = 0$ .
  - 3. For  $r = r_{n+1} \varepsilon$  the solution to the right of  $P_c$  intersects the line  $D_Z = 0$ .

For  $\gamma > 1$ , this is shown for n = 3, for  $\gamma = \frac{7}{5}$ , this is shown for odd n sufficiently large.

### **Barriers**

 $b^{\infty}$ 



The 
$$\gamma = \frac{7}{5}$$
 case

- ▶ For  $\gamma < \frac{5}{3}$  and fixed n,  $(W_n, Z_n)$  converge as  $r \to r^*$  in a non-trivial manner.
- The *wiggle* can be determined from the sign and a lower bound on the coefficients of order O(k).
- ▶ Via a computer assisted proof, compute the first 10000 coefficients with effective error bounds at  $r^*$  ( $Z_{10000} \sim 6 \times 10^{46770}$ ).
- ► The proof works for general  $\gamma < \frac{5}{3}$ ; however, the computation degenerates as  $\gamma \to \frac{5}{3}$ .

### Strategy for stability for Euler and Navier-Stokes

#### The basic strategy is:

- 1. Linearize Euler/Navier-Stokes around self-similar profiles.
- 2. Show the linearized operator as finitely many unstable modes.
- A Brouwer fix point argument shows there exists a manifold of initial data of finite co-dimension leading to imploding asymptotically self-similar blow-up.

Write

$$w(R,t) = r^{-1} (T-t)^{r^{-1}-1} \mathcal{W}(\frac{R}{(T-t)^{\frac{1}{r}}}, -\frac{\log(T-t)}{r})$$
$$z(R,t) = r^{-1} (T-t)^{r^{-1}-1} \mathcal{Z}(\frac{R}{(T-t)^{\frac{1}{r}}}, -\frac{\log(T-t)}{r}).$$

and define the self-similar variables

$$s = -\frac{\log(T-t)}{r}, \quad \zeta = \frac{R}{(T-t)^{\frac{1}{r}}} = e^s R = \exp(\xi).$$

The Navier-Stokes equations ( $\mu_1 = 1$  and  $\mu_2 = -1$ ) become

$$\begin{split} &(\partial_{s}+r-1)\mathcal{W}+(\zeta+\frac{1}{2}(\mathcal{W}+\mathcal{Z}+\alpha(\mathcal{W}-\mathcal{Z})))\partial_{\zeta}\mathcal{W}+\frac{\alpha}{2\zeta}(\mathcal{W}^{2}-\mathcal{Z}^{2})\\ &=\frac{r^{1+\frac{1}{\alpha}}2^{1/\alpha}}{\alpha^{1/\alpha}\zeta^{2}((\mathcal{W}-\mathcal{Z}))^{\frac{1}{\alpha}}}e^{(2-r+\frac{1}{\alpha}(1-r))s}\left(\partial_{\zeta}(\zeta^{2}\partial_{\zeta}(\mathcal{W}+\mathcal{Z}))-2(\mathcal{W}+\mathcal{Z})\right)\\ &(\partial_{s}+r-1)\mathcal{Z}+(\zeta+\frac{1}{2}(\mathcal{W}+\mathcal{Z}-\alpha(\mathcal{W}-\mathcal{Z})))\partial_{\zeta}\mathcal{Z}-\frac{\alpha}{2\zeta}(\mathcal{W}^{2}-\mathcal{Z}^{2})\\ &=\frac{r^{1+\frac{1}{\alpha}}2^{1/\alpha}}{\alpha^{1/\alpha}\zeta^{2}((\mathcal{W}-\mathcal{Z}))^{\frac{1}{\alpha}}}e^{(2-r+\frac{1}{\alpha}(1-r))s}\left(\partial_{\zeta}(\zeta^{2}\partial_{\zeta}(\mathcal{W}+\mathcal{Z}))-2(\mathcal{W}+\mathcal{Z})\right) \end{split}$$

If  $2 - r + \frac{1}{\alpha}(1 - r) < 0$  then the dissipation term is an exponentially decaying error term, i.e.

$$r>\frac{2\gamma}{\gamma+1},$$
.

Recall  $1 < r < r^*$ . Then, the adiabatic exponents are restricted to

$$1 < \gamma < \frac{2+\sqrt{3}}{\sqrt{3}}$$

.

#### Linearization

Let  $(\overline{W}, \overline{Z})$  be an exact, self-similar Euler profile and define  $(\widetilde{W}, \widetilde{Z}) = (\mathcal{W} - \overline{W}, \mathcal{Z} - \overline{Z})$ . Rewrite Euler/NS in linearized form

$$\partial_s \widetilde{W} = \mathcal{L}_W(\widetilde{W}, \widetilde{Z}) + \mathcal{F}_W \quad \text{and} \quad \partial_s \widetilde{Z} = \mathcal{L}_W(\widetilde{W}, \widetilde{Z}) + \mathcal{F}_Z$$

where  $(\mathcal{F}_W, \mathcal{F}_Z)$  include nonlinear and dissipative terms.

- ▶ We study the linearized operator  $\mathcal{L} = (\mathcal{L}_W, \mathcal{L}_Z)$
- It is also sometimes useful to write the operator in terms of self-similar velocity  $\mathcal{U}$  and sound speed  $\mathcal{S}$ , so that  $\mathcal{L} = (\mathcal{L}_{\mathcal{U}}, \mathcal{L}_{\mathcal{S}})$

### Strategy for linear stability

- 1. Causality is used to cut-off the linearized equation on a neighborhood of the backwards acoustic cone ( $|\zeta| \le 1$ ). Redefine  $\mathcal{L}$  using cut-offs.
- 2. Show that for large m and small  $\delta_g > 0$ ,  $\mathcal{L}$  decomposes as

$$\mathcal{L} = A = A_0 - \delta_g + K$$

for some  $A_0$  maximally dissipative on  $H_{\text{Rad}}^m$  and K is some compact.

- 3. Use (U, S) variables for high derivative energy estimates (dissipativity) and (W, Z) for low derivative arguments (maximality).
- 4. Lumer-Phillips theorem ensures exponential decay modulo a finite dimensional unstable space.

#### **Theorem**

Let  $\delta > 0$ , and T the (strongly continuous) semigroup generated by  $A = A_0 - \delta + K$  where  $A_0 : H \to H$  is a maximally dissipative operator and  $K : H \to H$  is compact. Then, there are finitely many eigenvalues  $\lambda_i$  with  $Re(\lambda_i) \geqslant 0$ .

Let  $\psi_i \in H$  be the corresponding eigenfunctions, let V be the finite dimensional space  $V = span(\psi_i)$ . There exists  $U \subset H$  such that U, V are invariant spaces of A and  $H = U \oplus V$ . Moreover

$$\|T(t)X\| \leqslant Ce^{-\delta t/2}\|X\|$$

for all  $X \in U$ 



### Dissipativity

Aim is to show that for (U,S) in a finite co-dim subspace of  $H^m_{\mathrm{Rad}}[0,2]$ 

$$\langle \mathcal{L}(U, S), (U, S) \rangle_{H^m} \leqslant - \|(U, S)\|_{H^m}^2$$

- Highest order terms cancel.
- ▶ Left over with *m*th order terms have a good sign, if *m* is large.
- Projecting away low frequencies controls lower order terms.

### Nonlinear stability argument

- 1. Control on unstable modes of truncated equations ⇒ global control on low order derivatives.
- 2. Global control on low order derivatives  $\implies$  global control on high order derivatives.
- 3. Global control on high order derivatives  $\implies$  dissipation can be treated as an decaying forcing term for the linearized problem.
- 4. Topological argument closes the argument, leading to a global solution of the self-similar equation.

### Topological argument

Let  $\{\psi_i\}_{i=1,...,N}$  be a basis for the unstable manifold and

$$\kappa_i = \langle (\widetilde{U}, \widetilde{S}), \psi_i \rangle$$

be the unstable modes of a solution. Let  $\mathcal{R}(s) = B_{\mathbb{R}^N}(0, e^{-\delta s})$ . If  $\kappa \in \partial \mathcal{R}$ , we can show that  $\kappa$  leaves  $\mathcal{R}$  immediately.

Consider solutions with initial unstable modes  $\kappa(s_0) \in \mathcal{R}(s_0)$ . Suppose all such initial data leave  $\mathcal{R}$  in finite time. This would imply (after rescaling) the existence of a continuous map from  $B_{\mathbb{R}^N}(0,1)$  to  $\mathcal{S}^{N-1}$ , which leads to a contradiction.

### Computer assisted arguments

Computer assisted interval arithmetic is used to prove the positivity of certain quantities: e.g. positivity of a polynomial over finite interval (barrier arguments) or the sign of a Taylor coefficient.

We define an arithmetic such that for intervals X, Y and  $x \in X$ ,  $y \in Y$ 

$$x \star y \in X \star Y$$
.

for a given operator ⋆. E.g.

$$\begin{split} & [\underline{x}, \overline{x}] + [\underline{y}, \overline{y}] = [\underline{x} + \underline{y}, \overline{x} + \overline{y}] \\ & [\underline{x}, \overline{x}] \times [\underline{y}, \overline{y}] = [\min\{\underline{x}\underline{y}, \underline{x}\overline{y}, \overline{x}\underline{y}, \overline{x}\overline{y}\}, \max\{\underline{x}\underline{y}, \underline{x}\overline{y}, \overline{x}\underline{y}, \overline{x}\overline{y}\}]. \end{split}$$

### Thank you!