Γ–limit for zigzag walls

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NYUAD











Pattern forming systems





NaCl crystal

Magnetic domains in iron bar



Polymer phase separation in poor solvent



Actin cytosceleton

Understand these patterns by minimization principle?

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Formation of magnetic domains in magnetic materials



Hubert & Schäfer, Magnetic Domains

Magnetization direction given unit vector |M| = 1.

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Complex transition layers in ferrromagnetic films



Cross tie wall



Zigzag wall

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- Ansatz based optimization of 1-d charged domain walls Hubert '79
- Néel wall Garcia-Cervera '04, Melcher '03, '04, DeSimone, HK, Otto '06, Ignat, Otto '08
- Cross-tie wall Alouges, Riviere, Serfaty '02, '03
- Zigzag domain walls in bulk materials (different effect) Ignat, Moser '12
- Asymmetric Bloch/Néel wall is asymptotically 1d. Döring, Ignat, Otto '14

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The micromagnetic energy of a ferromagnetic sample $\Omega \subset \mathbb{R}^3$ with magnetization $M : \mathbb{R}^3 \to \mathbb{R}^3$, $|M| = \chi_\Omega$ is given by (Landau, Lifshitz '35)

$$\mathcal{E}[M] = d^2 \int_{\Omega} |\nabla M|^2 dx + Q \int_{\Omega} (M_1^2 + M_2^2) dx + \int_{\mathbb{R}^3} |\nabla \varphi|^2 dx$$

Stray field energy and stray field $\nabla \varphi$ determined by

 $-\Delta \varphi = -\operatorname{div} M$

In analogy to electrostatics div M are called magnetic charges

- Exchange energy prefers uniform magnetization
- Anisotropy energy prefers orientation $M \approx \pm e_3$.
- Stray field energy prefers charge free configurations

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Geometry.

- Consider thin–film of form $\Omega = \underbrace{\mathbb{R} \times \mathbb{T}_{\ell}}_{=:Q_{\ell}} \times [0, t].$
- thin film regime $t \ll d$
- ℓ periodicity in x_2 with torus $\mathbb{T}_{\ell} := \mathbb{R}/[0, \ell)$.
- Enforce charged transition layer by boundary conditions

 $m = \pm e_1$ for $\pm x_1 > 1$.

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uncharged domain wall

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With this geometry the energy can be simplified.

$$m_3 = 0, \quad m \neq m(x_3).$$

Stray field approximation

$$\int_{\mathbb{R}^3} \left| \nabla \varphi \right|^2 = \int_{\mathbb{R}^3} \left| \left| \nabla \right|^{-1} \operatorname{div} m \right|^2 \approx \int_{\mathbb{R}^2} \left| \left| \nabla \right|^{-\frac{1}{2}} \operatorname{div} m \right|^2$$

Introduce background magnetization $M \in C^1(Q_\ell; \mathbb{S}^1)$ to ensure net charge zero, i.e.

$$\int_{Q_{\ell}} \operatorname{div}(m-M) \, dx = 0.$$

Reduced non-dimensionalized two-dim energy

$$E_{\varepsilon}[m] = \frac{1}{2} \int_{Q_{\ell}} \varepsilon |\nabla m|^2 dx + \frac{1}{2} \int_{Q_{\ell}} \frac{1}{\varepsilon} |m \cdot e_2|^2 dx + \frac{\pi \lambda}{2|\ln \varepsilon|} \int_{Q_{\ell}} \left| |\nabla|^{-\frac{1}{2}} \operatorname{div}(m-M) \right|^2 dx$$

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Classical phase transformation theory of Ginzburg-Landau

For prescribed volume $\int_{\Omega} u = \lambda$ consider

$$\mathcal{E}^{GL}_{\varepsilon}[u] = \varepsilon \int_{\Omega} |\nabla u(x)|^2 dx + \frac{1}{\varepsilon} \int_{\Omega} (1 - u^2(x))^2 dx.$$

Do minimizers converge to minimizers of a limit problem?





For $\varepsilon \to 0$ we have Γ -convergence in L^1 from the diffuse to a sharp interfact functional (Modica, Mortola '87)

$$\begin{array}{lll} \mathcal{E}_{\varepsilon}^{GL} & \stackrel{\Gamma}{\longrightarrow} & \mathcal{E}_{0}^{GL}, \\ \\ \mathcal{E}_{0}^{GL}[u] & := & c_{w} \int_{\Omega} |\nabla u| \; dx \qquad \text{with } |u| = 1 \end{array}$$



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 $\begin{array}{ll} \Gamma-\text{limit} \ (\text{DeGiorgi}): \ X \ \text{metric space}, \ \mathcal{E}_k : X \to \mathbb{R}. \ \text{Then} \ \mathcal{E}_k \xrightarrow{\Gamma} \mathcal{E}_0 \ \text{if} \\ (1) \ \text{For any} \ u \in X \ \text{there is a sequence} \ u_{\varepsilon} \ \text{with} \ u_{\varepsilon} \to u \ \text{and} \\ & \lim_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}[u_{\varepsilon}] \leq \mathcal{E}_0[u] & \text{limsup inequality} \\ (2) \ \text{For any sequence} \ u_{\varepsilon} \ \text{with} \ u_{\varepsilon} \to u, \ \text{we have} \\ & \lim_{\varepsilon \to 0} \mathcal{E}_{\varepsilon}[u_{\varepsilon}] \geq \mathcal{E}_0[u] & \text{liminf inequality} \end{array}$





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Γ-limit (DeGiorgi): X metric space, E_k : X → ℝ. Then E_k → E₀ if
(1) For any u ∈ X there is a sequence u_ε with u_ε → u and
lim sup E_ε[u_ε] ≤ E₀[u] limsup inequality
(2) For any sequence u_ε with u_ε → u, we have
lim inf E_ε[u_ε] ≥ E₀[u] liminf inequality





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Main result

Initial model: We recall our energy

$$E_{\varepsilon}[m] = \frac{1}{2} \int_{Q_{\ell}} \varepsilon |\nabla m|^2 \, dx + \frac{1}{2} \int_{Q_{\ell}} \frac{1}{\varepsilon} |m \cdot e_2|^2 \, dx + \frac{\pi \lambda}{2|\ln \varepsilon|} \int_{Q_{\ell}} ||\nabla|^{-\frac{1}{2}} \operatorname{div}(m-M)|^2 \, dx$$

Compactness: Every sequence with bounded energy is L^1 -compact with limits in

$$\mathcal{A}_0 = \{m = (u, 0) \in BV_{loc}(Q_\ell; \{\pm e_1\}) : m = \pm e_1 \text{ for } \pm x_1 > 1\}.$$

For $m \in \mathcal{A}_0$, the jump set is denoted by \mathcal{S}_m and its outer normal by n.

Theorem 1 (Γ–convergence)

Let $\lambda \geq 0$. Then $E_{\varepsilon} \stackrel{i}{\longrightarrow} E_0$ in the L^1 -topology, where

$$E_0[m] = 2 \int_{\mathcal{S}_m} \left(1 + (\sqrt{\lambda} |e_1 \cdot n|)^2 \right) \chi_{\{|e_1 \cdot n| \le \frac{1}{\sqrt{\lambda}}\}} + 2\sqrt{\lambda} |e_1 \cdot n| \chi_{\{|e_1 \cdot n| > \frac{1}{\sqrt{\lambda}}\}} \ d\mathcal{H}^1$$

if $m \in A_0$ and $E_0[m] = +\infty$ otherwise.

- Perimeter and nonlocal term have same scaling since $|
 abla m| \sim |
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A look at the limit model

We note that the limit energy is local

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The minimal energy for $m \in \mathcal{A}_0$ is

$$\min_{m \in \mathcal{A}_0} E_0[m] = 2\ell \begin{cases} (1+\lambda) & \text{if } \lambda \leq 1, \\ 2\sqrt{\lambda} & \text{if } \lambda > 1. \end{cases}$$

Anisotropic penalization of jump singularities in the limit, allows for zigzags

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A look at the limit model

We note that the limit energy is local

$$E_0[m] = 2 \int_{\mathcal{S}_m} \left(1 + \left(\sqrt{\lambda} | \boldsymbol{e}_1 \cdot \boldsymbol{n} | \right)^2 \right) \chi_{\{|\boldsymbol{e}_1 \cdot \boldsymbol{n}| \le \frac{1}{\sqrt{\lambda}}\}} + 2\sqrt{\lambda} | \boldsymbol{e}_1 \cdot \boldsymbol{n} | \chi_{\{|\boldsymbol{e}_1 \cdot \boldsymbol{n}| > \frac{1}{\sqrt{\lambda}}\}} \ d\mathcal{H}^1$$

Global minimizers are those (non-unique) configurations, where the jump set is a graph with

$$|n \cdot e_1| \geq \min\{1, \lambda^{-\frac{1}{2}}\}.$$



The minimal energy for $m \in A_0$ is

$$\min_{m \in \mathcal{A}_0} E_0[m] = 2\ell \begin{cases} (1+\lambda) & \text{if } \lambda \leq 1, \\ 2\sqrt{\lambda} & \text{if } \lambda > 1. \end{cases}$$

Anisotropic penalization of jump singularities in the limit, allows for zigzags

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